Design Principles of Programming Languages

Type Reconstruction

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Type Reconstruction

- A controversial feature
  - Pros: less typing, yeah!
    - Map<String, List<Pair<Token, SrcInfo>>>
  - Cons: more difficult to debug type errors
    - No type declaration as central concept

- Yet worth studying
  - Understanding the potentials of compilers
  - Closely related to polymorphism

An Example

- $g = \lambda a. \lambda f. iszero\ (f\ a)$
- $h = g\ 10$

- What is the types of a, f, g, h?

Introducing Type Variables

- $g = \lambda a : X . \lambda f : Y . iszero\ (f\ a)$
- $h = g\ 10$

Generating Constraints

- $g = \lambda a{:}X.\lambda f{:}Y.iszero\ (f\ a)$
- $h = g\ 10$

- $Y = X \rightarrow Z_0$
- $Nat = Z_0$
- $X \rightarrow Y \rightarrow Bool = Nat \rightarrow Z_1$

Unification

- $g = \lambda a : X. \lambda f : Y. iszero\ (f\ a)$
- $h = g\ 10$

- $Y = X \rightarrow Z_0$
- $Nat = Z_0$
- $X \rightarrow Y \rightarrow Bool = Nat \rightarrow Z_1$

- $X = Nat, Y = Nat \rightarrow Nat, Z_0 = Nat, Z_1 = (Nat \rightarrow Nat) \rightarrow Bool$

By typing rules

- $g = \lambda a{:}X.\lambda f{:}Y.iszero\ (f\ a)$
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- $Y = X \rightarrow Z_0$
- $Nat = Z_0$
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- $X = Nat, Y = Nat \rightarrow Nat, Z_0 = Nat, Z_1 = (Nat \rightarrow Nat) \rightarrow Bool$
- $g{:}Nat \rightarrow (Nat \rightarrow Nat) \rightarrow Bool$
- $h{:}(Nat \rightarrow Nat) \rightarrow Bool$

Type Variables

- New Syntactic Rule

  t ::= …

      λx. t   // untyped lambda abstraction

  T ::= …

      X   // type variables

Type Substitution

- A finite mapping from type variables to types
  - $\sigma = [X \mapsto Bool, Y \mapsto Nat \rightarrow Nat]$
  - Note the difference between $\mapsto$ and $\rightarrow$

- Application of substituation σ

$$\sigma(X) = \begin{cases} T & \text{if } (X \mapsto T) \in \sigma \\ X & \text{if X is not in the domain of } \sigma \end{cases}$$

$$\sigma(\text{Nat}) = \text{Nat}$$

$$\sigma(\text{Bool}) = \text{Bool}$$

$$\sigma(T_1 \rightarrow T_2) = \sigma T_1 \rightarrow \sigma T_2$$

Preservation of Typing under Type Substitution

$$\frac{\sigma : \text{any type substitution} \qquad \Gamma \vdash t: T}{\sigma\Gamma \vdash \sigma t: T}$$

- Proof: By induction on typing rules

Solution

- A solution for (Γ, t) is a pair (σ, T) such that $\sigma\Gamma \vdash \sigma t : T$

EXAMPLE: Let $\Gamma = f:X, a:Y$ and $t = f\ a$. Then

$([X \mapsto Y{\to}Nat],\ Nat)$ $\qquad$ $([X \mapsto Y{\to}Z],\ Z)$

$([X \mapsto Y{\to}Z,\ Z \mapsto Nat],\ Z)$ $\qquad$ $([X \mapsto Y{\to}Nat{\to}Nat],\ Nat{\to}Nat)$

$([X \mapsto Nat{\to}Nat, Y \mapsto Nat],\ Nat{\to}Nat)$

are all solutions for (Γ, t).

- Problem: which one is better?

Principal Types

- Substitution σ is more general than σ', written $\sigma \sqsubseteq \sigma'$ iff $\sigma' = \gamma \circ \sigma$ for some γ.

- Substitution σ is more general than σ' for term t, written $\sigma \sqsubseteq_t \sigma'$ iff $\sigma' t = \gamma(\sigma t)$ for some γ.

- A most general substitution leads to a principle type

EXAMPLE: Let $\Gamma = $ f:X, a:Y and t = f a. Then

$([X \mapsto Y \rightarrow Nat],\ Nat)$ $([X \mapsto Y \rightarrow Z],\ Z)$

$([X \mapsto Y \rightarrow Z,\ Z \mapsto Nat],\ Z)$ $([X \mapsto Y \rightarrow Nat \rightarrow Nat],\ Nat \rightarrow Nat)$

$([X \mapsto Nat \rightarrow Nat,\ Y \mapsto Nat],\ Nat \rightarrow Nat)$

are all solutions for (Γ, t).

- Which are most general substituions?

Principal Types

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are all solutions for (Γ, t).

- Which one is a most general one?
  1. Replacing less variables
  2. Replacing with less specific types

Constraint Set

- A constraint set is a set of equations $\{S_i = T_i\}$.

- σ satisfy C=$\{S_i = T_i\}$ when $\sigma S_i = \sigma T_i$ for all i.

Constraint Typing Rules

- $$\frac{x{:}T\in\Gamma}{\Gamma\vdash x{:}T|\{\}}$$

- $$\frac{\Gamma,x{:}T_1\vdash t_2{:}T_2|C}{\Gamma\vdash\lambda x{:}T_1.t_2{:}T_1{\to}T_2|C}$$

- X is a fresh type variable
$$\frac{\Gamma,x{:}X\vdash t{:}T|C}{\Gamma\vdash\lambda x.t{:}X{\to}T|C}$$

- $\Gamma\vdash t_1{:}T_1|C_1 \qquad \Gamma\vdash t_2{:}T_2|C_2$
X is a fresh type variable
$$\frac{}{\Gamma\vdash t_1\,t_2{:}X|C_1\cup C_2\cup\{T_1{=}T_2{\to}X\}}$$

- $$\frac{}{\Gamma\vdash 0{:}Nat|\{\}}$$

- $$\frac{}{\Gamma\vdash true{:}Bool|\{\}}$$

- $$\frac{}{\Gamma\vdash false{:}Bool|\{\}}$$

- $$\frac{\Gamma\vdash t_1{:}T|C}{\Gamma\vdash succ\,t_1{:}Nat|C\cup\{T{=}Nat\}}$$

- $$\frac{\Gamma\vdash t_1{:}T|C}{\Gamma\vdash pred\,t_1{:}Nat|C\cup\{T{=}Nat\}}$$

- $$\frac{\Gamma\vdash t_1{:}T|C}{\Gamma\vdash iszero\,t_1{:}Nat|C\cup\{T{=}Nat\}}$$

- $\Gamma\vdash t_1{:}T_1|C_1 \quad \Gamma\vdash t_2{:}T_2|C_2 \quad \Gamma\vdash t_3{:}T_3|C_3$
$C'{=}C_1\cup C_2\cup C_3\cup\{T_1{=}Bool,T_2{=}T_3\}$
$$\frac{}{\Gamma\vdash if\,t_1\,then\,t_2\,else\,t_3{:}T_2|C'}$$

* In the book, the freshness of type variables are also treated formally in the rules

Exercise

- Deduce constraints for
  - $\lambda f.\lambda n.if\ iszero\ n\ then\ f\ n\ else\ n$

Soundness and Completeness

- Suppose that $\Gamma \vdash t : S \mid C$. A solution for (Γ, t, S, C) is a pair (σ, T) such that σ satisfies C and $\sigma S = T$.
- Soundness
  - If (σ, T) is a solution for (Γ, t, S, C), then it is also a solution for (Γ, t).
  - Proof: by induction on constraint typing rules
- Completeness
  - If (σ, T) is a solution for (Γ, t), then there exists solution (σ', T) for (Γ, t, S, C) where σ and σ' are the same for any type variables in t.
  - Proof: by induction on constraint typing rules

Unification Algorithm

$$unify(C) \quad = \quad \text{if } C = \emptyset, \text{ then } [\,]$$

else let $\{S = T\} \cup C' = C$ in

    if S is T

        then $unify(C')$

    else if S is X and $X \notin FV(T)$

        then $unify([X \mapsto T]C') \circ [X \mapsto T]$

    else if T is X and $X \notin FV(S)$

        then $unify([X \mapsto S]C') \circ [X \mapsto S]$

    else if S is $S_1 \rightarrow S_2$ and T is $T_1 \rightarrow T_2$

        then $unify(C' \cup \{S_1 = T_1, S_2 = T_2\})$

    else

        fail

Soundness

- The unification algorithm returns a most general substitution if there is one, or fails otherwise.
  - Proof: Induction on the number of recursive calls

Termination

- Every iteration either
    - drop a constraint from C, or
    - divide a constraint into smaller constraints

Type Reconstruction with Subtyping

- Constraints containing both <: and =
- Every type variable starts with TOP
- Shrink types to satisfy constraints
  - X:Nat, Y:TOP $\xrightarrow{X=Y}$ X:Nat, Y:Nat
  - X:Nat, Y:TOP $\xrightarrow{X<:Y}$ X:Nat, Y:TOP
  - X:Nat, Y:TOP $\xrightarrow{X:>Y}$ X:Nat, Y:Nat
- Until a fixed point is reached
- Termination
  - Types for the variables are always shrink
  - Lower bound exist

Polymorphism

- let double=λf. λa. f (f a) in
  {
    double (λx:Nat. succ (succ x)) 1,
    double (λx:Bool x) false
  }

- Will this program be type checked?

$$\frac{\Gamma \vdash t_1 : T_1 \qquad \Gamma, x:T_1 \vdash t_2 : T_2}{\Gamma \vdash \text{let } x=t_1 \text{ in } t_2 : T_2}$$

Three types of polymorphisms

- Polymorphism
  - A single interface to different types
- Adhoc Polymorphism
  - e.g., case…of…, function overloading

  double f:Nat->Nat a:Nat = f (f a)
  double f:Bool->Bool a:Bool = f (f a)
- Subtyping

  ```
  interface function {
        Object apply(Object);
        Object doubleApply(Object);
  }
  ```
- Parametric Polymorphism
  - e.g., C++ template

Hindley-Milner Type System

- A simple polymorphism type system deals with the previous case

- Widely-used in some mainstream functional programming languages
  - Ocaml, ML, Haskell98.

- Weaker than System-F to be introduced in the next course
  - Type reconstruction is undecidable for System-F.

Typing Rules in HM-System

$$\frac{\Gamma \vdash t_1 : T_1 \qquad \Gamma, x{:}T_1 \vdash t_2 : T_2}{\Gamma \vdash \text{let } x=t_1 \text{ in } t_2 : T_2}$$

$$\frac{\Gamma \vdash [x \mapsto t_1]t_2 : T_2 \quad |_x\ C}{\Gamma \vdash \text{let } x=t_1 \text{ in } t_2 : T_2 \quad |_x\ C}$$

Exercise

- What is the type of this program?

- let f = λx.x in
  let g = λx.f (f x) in
  {g 5, g true}

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- (λf.
  let g = λx.f (f x) in
  {g 5, g true}
) (λx.x)

Exercise

- What is the type of this program?

- let h= λx.x in
  (λf.
  let g = λx.f (f x) in
  {g 5, g true}
) h

Inefficiency of the typing rules

- let double=λf. λa. f (f a) in
  {
      double (λx:Nat. succ (succ x)) 1,
      double (λx:Bool x) false
  }

- The red part is type checked twice

A more efficient algorithm

- let double=λf. λa. f (f a) in
  {
    double (λx:Nat. succ (succ x)) 1,
    double (λx:Bool x) false
  }

1. Type check only the "let" part (red) and get its principle type
   - (X→X)→X →X

A more efficient algorithm

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   - (X→X)→X →X

2. Introduce quantification for type variables not used in Γ
   - double: ∀X.(X→X)→X →X

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2. Introduce quantification for type variables not used in Γ
   - double: ∀X.(X→X)→X →X

3. Add it to Γ and type check the body, using an additional typing rule

$$\frac{t: \forall X_1 \dots X_n. T \in \Gamma \quad Y_1 \dots Y_n \text{ are fresh variables}}{\Gamma \vdash t: [X_1 \mapsto Y_1] \dots [X_n \mapsto Y_n] T}$$

A more efficient algorithm

- The informal description does not work with the formal system in the text book
  - Need to reformulate all rules to make it formal
- For full formal description, see Wikipedia page of "Hindley-Milner type system"

Ref variables

- What is the type of the following program?
  - let r=ref (λx.x) in
    (r:=(λx:Nat, succ x); (!r)true);

Ref variables

- What is the type of the following program?
  - let r=ref (λx.x) in
    (r:=(λx:Nat, succ x); (!r)true);

- HM-system does not work with ref variables

- Disallow polymorphism when the let definition is of reference type

Homework

- Change the constraint typing rule and the unification algorithm so that the following term can be typed
  - fix (λh. λx:Nat. h)