To Discuss

项目组队情况

作业

课程的建议
Recap on References
Syntax

We added to $\lambda \rightarrow$ (with Unit) syntactic forms for creating, dereferencing, and assigning reference cells, plus a new type constructor Ref.

\[
t ::= \\
  \text{unit} \\
x \\
\lambda x:T.t \\
t \ t \\
\text{ref} \ t \\
!t \\
t := t \\
/ \\
\]

\[
\text{terms} \\
  \text{unit constant} \\
  \text{variable} \\
  \text{abstraction} \\
  \text{application} \\
  \text{reference creation} \\
  \text{dereference} \\
  \text{assignment} \\
  \text{store location}
\]
Evaluation becomes a four-place relation: \( t | \mu \rightarrow t' | \mu' \)

\[
\frac{l \notin \text{dom}(\mu)}{\text{ref } v_1 | \mu \rightarrow l | (\mu, \ l \mapsto v_1)} \quad \text{(E-RefV)}
\]

\[
\frac{\mu(l) = v}{!l | \mu \rightarrow v | \mu} \quad \text{(E-DerefLoc)}
\]

\[
l:=v_2 | \mu \rightarrow \text{unit} | [l \mapsto v_2]\mu \quad \text{(E-Assgn)}
\]
Typing becomes a *three-place* relation: $\Gamma \mid \Sigma \vdash t : T$

\[
\Sigma(l) = T_1 \\
\frac{}{\Gamma \mid \Sigma \vdash l : \text{Ref} \ T_1}
\]

\[
\Gamma \mid \Sigma \vdash t_1 : T_1 \\
\frac{}{\Gamma \mid \Sigma \vdash \text{ref} \ t_1 : \text{Ref} \ T_1}
\]

\[
\Gamma \mid \Sigma \vdash t_1 : \text{Ref} \ T_{11} \\
\frac{}{\Gamma \mid \Sigma \vdash !t_1 : T_{11}}
\]

\[
\Gamma \mid \Sigma \vdash t_1 : \text{Ref} \ T_{11} \quad \Gamma \mid \Sigma \vdash t_2 : T_{11} \\
\frac{}{\Gamma \mid \Sigma \vdash t_1 := t_2 : \text{Unit}}
\]

(T-Loc)

(T-Ref)

(T-Deref)

(T-Assign)
Preservation

**Theorem:** if

\[ \Gamma \mid \Sigma \vdash t : T \]
\[ \Gamma \mid \Sigma \vdash \mu \]
\[ t \mid \mu \rightarrow t' \mid \mu' \]

then, for some \( \Sigma' \supseteq \Sigma \),

\[ \Gamma \mid \Sigma' \vdash t' : T \]
\[ \Gamma \mid \Sigma' \vdash \mu'. \]
Progress

*Theorem:* Suppose $t$ is a *closed, well-typed* term (that is, \( \varnothing \vdash t : T \) for some $T$ and $\Sigma$). Then either $t$ is a value or else, for any store $\mu$ such that $\varnothing \vdash \mu$, there is some term $t'$ and store $\mu'$ with $t \mid \mu \rightarrow t' \mid \mu'$. 
Nontermination via references

There are well-typed terms in this system that are not strongly normalizing. For example:

\[ t_1 = \lambda r: \text{Ref} (\text{Unit} \rightarrow \text{Unit}). \]
\[
(r := (\lambda x: \text{Unit}. (! r)x); \]
\[
(! r) \text{ unit}); \]
\[ t_2 = \text{ref} (\lambda x: \text{Unit}. x); \]

Applying \( t_1 \) to \( t_2 \) yields a (well-typed) divergent term.
Nontermination via references

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\[ (! r) \text{unit}); \]
\[ t2 = \text{ref} (\lambda x: \text{Unit}. x); \]

Applying \( t1 \) to \( t2 \) yields a (well-typed) divergent term.
Recursion via references

Indeed, we can define arbitrary recursive functions using references.

1. Allocate a ref cell and initialize it with a dummy function of the appropriate type:
   \[ \text{fact}_{ref} = \text{ref} (\lambda n: \text{Nat}. 0) \]

2. Define the body of the function we are interested in, using the contents of the reference cell for making recursive calls:
   \[ \text{fact}_{body} = \lambda n: \text{Nat}. \]
   \[ \quad \text{if iszero n then 1 else times n } ((! \text{fact}_{ref})(\text{pred } n)) \]

3. “Backpatch” by storing the real body into the reference cell:
   \[ \text{fact}_{ref} := \text{fact}_{body} \]

4. Extract the contents of the reference cell and use it as desired:
   \[ \text{fact} = ! \text{fact}_{ref} \]
   \[ \text{fact } 5 \]
Chapter 14: Exceptions

Why exceptions
Raising exceptions
Handling exceptions
Exceptions carrying values
Exceptions
Why exceptions?

Real world programming is full of situations where a function needs to signal to its caller that it is unable to perform its task for:

- Division by zero
- Arithmetic overflow
- Array index out of bound
- Lookup key missing
- File could not be opened
- .....
Why exceptions?

Most programming languages provide some mechanism for interrupting the normal flow of control in a program to signal some exceptional condition.

Note that it is always possible to program without exceptions — instead of raising an exception, we return None; instead of returning result x normally, we return Some(x). But now we need to wrap every function application in a case to find out whether it returned a result or an exception.

It is much more convenient to build this mechanism into the language.
Why exceptions?

# type 'α list = None | Some of 'α
# let head l = match l with
    [] -> None
    | x::_ -> Some (x);;
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Type inference?
Why exceptions?

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Type inference?

# let head l = match l with
  | [] -> raise Not_found
  | x::_ -> x;;
Varieties of non-local control

There are many ways of adding “non-local control flow”

- `exit(1)`
- `goto`
- `setjmp/longjmp`
- `raise/try` (or `catch/throw`) in many variations
- `callcc / continuations`
- more esoteric variants (cf. many Scheme papers)

Let’s begin with the simplest of these.
An “abort” primitive in $\lambda$→

First step: raising exceptions (but not catching them).

Syntactic forms

\[ t ::= \ldots \quad \text{terms} \]
\[ \text{error} \quad \text{run-time error} \]

Evaluation

\[ \text{error } t_2 \rightarrow \text{error} \quad (E\text{-AppErr1}) \]

\[ v_1 \text{ error } \rightarrow \text{error} \quad (E\text{-AppErr2}) \]
Typing

\( \Gamma \vdash \text{error} : T \)  \hspace{2cm} (T-\text{ERROR})

**New syntactic forms**

\( t ::= \ldots \)

- error

**New evaluation rules**

- error \( t_2 \rightarrow \text{error} \)
- \( v_1 \text{ error} \rightarrow \text{error} \)

**New typing rules**

- \( \Gamma \vdash t : T \)
- \( \Gamma \vdash \text{error} : T \)  \hspace{2cm} (T-\text{ERROR})
Typing errors

Note that the typing rule for \texttt{error} allows us to give it \textit{any} type $T$.

\[ \Gamma \vdash \texttt{error} : T \] (T-Error)

What if we had booleans and numbers in the language?
Typing errors

Note that the typing rule for \texttt{error} allows us to give it \textit{any} type $T$.

\[
\Gamma \vdash \texttt{error} : T \quad \text{(T-Error)}
\]

What if we had booleans and numbers in the language?

This means that both

\[
\text{if } x > 0 \text{ then } 5 \text{ else } \texttt{error}
\]

and

\[
\text{if } x > 0 \text{ then } \texttt{true} \text{ else } \texttt{error}
\]

will typecheck.
Aside: Syntax-directedness

Note that this rule

\[ \Gamma \vdash \text{error} : T \]  \hspace{1cm} \text{(T-Error)}

has a *problem* from the point of view of implementation: it is not *syntax directed*.

This will cause the *Uniqueness of Types* theorem to fail.

For purposes of defining the language and proving its type safety, this is not a problem — Uniqueness of Types is not critical.

Let’s think a little about how the rule might be fixed...
Aside: Syntax-directed rules

When we say a set of rules is syntax-directed we mean two things:

1. There is *exactly one rule* in the set that applies to each syntactic form. (We can tell by the syntax of a term which rule to use.)
   - In order to derive a type for $t_1 t_2$, we must use T-App.

2. We don't have to "guess" an input (or output) for any rule.
   - To derive a type for $t_1 t_2$, we need to derive a type for $t_1$ and a type for $t_2$. 
An alternative

Can’t we just decorate the error keyword with its intended type, as we have done to fix related problems with other constructs?

\[ \Gamma \vdash (\text{error as } T) : T \]  

(T-Error)
An alternative

Can’t we just decorate the error keyword with its intended type, as we have done to fix related problems with other constructs?

\[ \text{Γ} \vdash (\text{error as } T) : T \quad (T\text{-Error}) \]

No, this doesn’t work!

E.g. (assuming our language also has numbers and booleans):

\[
\text{succ (if (error as Bool) then 3 else 8)} \quad \rightarrow \text{succ (error as Bool)}
\]
Another alternative

In a system with universal polymorphism (like OCaml), the variability of typing for error can be dealt with by assigning it a variable type!

\[ \Gamma \vdash \text{error} : \ '\alpha \quad (T\text{-ERROR}) \]
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In a system with universal polymorphism (like OCaml), the variability of typing for error can be dealt with by assigning it a variable type!

\[ \Gamma \vdash \text{error} : '\alpha \quad (T\text{-ERROR}) \]

In effect, we are replacing the uniqueness of typing property by a weaker (but still very useful) property called most general typing.

I.e., although a term may have many types, we always have a compact way of representing the set of all of its possible types.
Yet another alternative

Alternatively, in a system with subtyping (which we’ll discuss next chapter) and a minimal Bot type, we can give error a unique type:
Yet another alternative

Alternatively, in a system with subtyping (which we’ll discuss next chapter) and a minimal Bot type, we can give error a unique type:

\[ \Gamma \vdash \text{error} : \text{Bot} \]

(Of course, what we’ve really done is just pushed the complexity of the old error rule onto the Bot type!)
For now...

Let’s stick with the original rule

\[ \Gamma \vdash \text{error} : T \quad \text{(T-Error)} \]

and live with the resulting nondeterminism of the typing relation.
Type safety

The preservation theorem requires no changes when we add error: if a term of type $T$ reduces to error, that’s fine, since error has every type $T$. 
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Progress, though, requires a little more care.
First, note that we do *not* want to extend the set of values to include *error*, since this would make our new rule for propagating errors through applications. 

\[
v_1 \text{ error } \rightarrow \text{ error} \quad \text{(E-AppErr2)}
\]

overlap with our existing computation rule for applications:

\[
(\lambda x: T_{11}. t_{12}) \ v_2 \rightarrow [x \mapsto v_2] t_{12} \quad \text{(E-AppAbs)}
\]

e.g., the term

\[
(\lambda x: \text{Nat. 0}) \text{ error}
\]
could evaluate to either 0 (which would be wrong) or *error* (which is what we intend).
Progress

Instead, we keep error as a non-value normal form, and refine the statement of progress to explicitly mention the possibility that terms may evaluate to error instead of to a value.

Theorem [Progress]: Suppose \( t \) is a closed, well-typed normal form. Then either \( t \) is a value or \( t = \text{error} \).
Catching exceptions

\[
t ::= \ldots \quad \text{terms} \\
\quad \text{try } t \text{ with } t \quad \text{trap errors}
\]

**Evaluation**

\[
\text{try } v_1 \text{ with } t_2 \rightarrow v_1 \quad (E-\text{TRYV})
\]

\[
\text{try error with } t_2 \rightarrow t_2 \quad (E-\text{TRYError})
\]

\[
\frac{t_1 \rightarrow t'_1}{\text{try } t_1 \text{ with } t_2 \rightarrow \text{try } t'_1 \text{ with } t_2} \quad (E-\text{TRY})
\]

**Typing**

\[
\Gamma \vdash t_1 : T \quad \Gamma \vdash t_2 : T \\
\frac{}{\Gamma \vdash \text{try } t_1 \text{ with } t_2 : T} \quad (T-\text{TRY})
\]
Exceptions carrying values

When something unusual happened, it’s useful to send back some extra information about which unusual thing has happened so that the handler can take some actions depending on this information.
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t ::= ... 
   raise t

terms
   raise exception
Exceptions carrying values

When something unusual happened, it’s useful to send back some extra information about which unusual thing has happened so that the handler can take some actions depending on this information.

```
t ::= ...
    raise t
```

Atomic term `error` is replaced by a term constructor
```
raise t
raise exception
```
where `t` is the extra information that we want to pass to the exception handler.
Evaluation

(\text{raise } v_{11}) \; t_2 \rightarrow \text{raise } v_{11} \quad \text{(E-AppRaise1)}

v_1 \; (\text{raise } v_{21}) \rightarrow \text{raise } v_{21} \quad \text{(E-AppRaise2)}

\frac{t_1 \rightarrow t'_1}{\text{raise } t_1 \rightarrow \text{raise } t'_1} \quad \text{(E-Raise)}

\text{raise } (\text{raise } v_{11}) \rightarrow \text{raise } v_{11} \quad \text{(E-RaiseRaise)}

\text{try } v_1 \text{ with } t_2 \rightarrow v_1 \quad \text{(E-TryV)}

\text{try } \text{raise } v_{11} \text{ with } t_2 \rightarrow t_2 \; v_{11} \quad \text{(E-TryRaise)}

\frac{t_1 \rightarrow t'_1}{\text{try } t_1 \text{ with } t_2 \rightarrow \text{try } t'_1 \text{ with } t_2} \quad \text{(E-Try)}
Evaluation

\[
\begin{align*}
(\text{raise } v_{11}) & \rightarrow \text{raise } v_{11} & (\text{E-APPRAISE1}) \\
v_1 (\text{raise } v_{21}) & \rightarrow \text{raise } v_{21} & (\text{E-APPRAISE2}) \\
    t_1 & \rightarrow t'_1 & (\text{E-RAISE}) \\
    \frac{\text{raise } t_1 \rightarrow \text{raise } t'_1}{t_1 \rightarrow t'_1} & \quad (\text{E-RAISERAISE}) \\
\text{raise } (\text{raise } v_{11}) & \rightarrow \text{raise } v_{11} & (\text{E-TRYV}) \\
\text{try } v_1 \text{ with } t_2 & \rightarrow v_1 & (\text{E-TRYRAISE}) \\
\text{try raise } v_{11} \text{ with } t_2 & \rightarrow t_2 v_{11} & (\text{E-TRY}) \\
    t_1 & \rightarrow t'_1 & (\text{E-TRY}) \\
    \frac{\text{try } t_1 \text{ with } t_2 \rightarrow \text{try } t'_1 \text{ with } t_2}{t_1 \rightarrow t'_1} & \quad (\text{E-TRY})
\end{align*}
\]
Typing

To typecheck *raise* expressions, we need to choose a type — let’s call it $T_{exn}$ — for the values that are carried along with exceptions.

\[
\begin{align*}
\Gamma \vdash t_1 : T_{exn} \\
\Gamma \vdash \text{raise } t_1 : T \\
(\text{T-Exn})
\end{align*}
\]

\[
\begin{align*}
\Gamma \vdash t_1 : T \\
\Gamma \vdash t_2 : T_{exn} \rightarrow T \\
\Gamma \vdash \text{try } t_1 \text{ with } t_2 : T \\
(\text{T-Try})
\end{align*}
\]
What is $T_{exn}$?

To complete the story, we need to decide what type to use as $T_{exn}$. There are several possibilities.
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1. Numeric error codes: $T_{exn} = \text{Nat}$ (as in C)
2. Error messages: $T_{exn} = \text{String}$
What is $T_{\text{exn}}$?

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1. Numeric error codes: $T_{\text{exn}} = \text{Nat}$ (as in C)
2. Error messages: $T_{\text{exn}} = \text{String}$
3. A predefined variant type:

\[
T_{\text{exn}} = \langle \text{divideByZero: Unit,} \\
\text{overflow: Unit,} \\
\text{FileNotFoundException: String,} \\
\text{FileNotFoundException: String,} \\
... \rangle
\]
What is $T_{exn}$?

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1. Numeric error codes: $T_{exn} = \text{Nat}$ (as in C)
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   $T_{exn} = \langle \text{divideByZero: Unit,} \$
   \text{overflow: Unit,} \$
   \text{fileNotFound: String,} \$
   \text{fileNotReadable: String,} \$
   \ldots \rangle$

4. An extensible variant type (as in Ocaml)
What is $T_{exn}$?

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   \text{FileNotFoundException: String,} \\
   \text{FileNotFoundException: String,} \\
   \ldots \rangle
   \]

4. An *extensible* variant type (as in Ocaml)
5. A *class* of “throwable objects” (as in Java)
Recapitulation: Error handling

New syntactic forms

\[ t ::= \ldots \]

\[ \text{try } t \text{ with } t \]

New evaluation rules

\[ \text{try } v_1 \text{ with } t_2 \rightarrow v_1 \]

\[ \text{try error with } t_2 \rightarrow t_2 \]

terms:

trap errors

\[ t \rightarrow t' \]

(E-TRY)

\[ \frac{t_1 \rightarrow t'_1}{\text{try } t_1 \text{ with } t_2 \rightarrow \text{try } t'_1 \text{ with } t_2} \]

(E-TRYV)

New typing rules

\[ \frac{\Gamma \vdash t : T}{\Gamma \vdash \text{try } t_1 \text{ with } t_2 : T} \]

(T-TRY)

Extends \( \lambda \) with errors (14-1)
Recapitulation: Exceptions carrying values

→ exceptions

New syntactic forms

\[ t ::= \ldots \]

- `raise t`
- `try t with t`

New evaluation rules

\( (\text{raise } v_{11}) \ t_2 \rightarrow \text{raise } v_{11} \)  \hspace{1cm} (E-APPRAISE1)
\( v_1 \ (\text{raise } v_{21}) \rightarrow \text{raise } v_{21} \)  \hspace{1cm} (E-APPRAISE2)
\( t_1 \rightarrow t'_1 \)
\( \frac{}{\text{raise } t_1 \rightarrow \text{raise } t'_1} \)  \hspace{1cm} (E-RAISE)
\( \text{raise } (\text{raise } v_{11}) \rightarrow \text{raise } v_{11} \)  \hspace{1cm} (E-RAISERAISE)
\( t \rightarrow t' \)
\( \frac{t_1 \rightarrow t'_1}{\text{try } t_1 \text{ with } t_2 \rightarrow \text{try } t'_1 \text{ with } t_2} \)  \hspace{1cm} (E-TRY)

New typing rules

\( \Gamma \vdash t : T \)  \hspace{1cm} (T-EXN)
\( \Gamma \vdash \text{raise } t_1 : T \)  \hspace{1cm} (T-TRY)
\( \Gamma \vdash \text{try } t_1 \text{ with } t_2 : T \)
Recapitulation

• Raising exception is more than an error mechanism: it’s a programmable control structure
  – Sometimes a way to quickly escape from the computation

• E.g., Exceptions are used in OCaml as a control mechanism, either to signal errors, or to control the flow of execution. When an exception is raised, the current execution is aborted, and control is thrown to the most recently entered active exception handler, which may choose to handle the exception, or pass it through to the next exception handler.
Examples in OCaml

# let rec assoc key = function
   (k, v) :: l ->
       if k = key then v
       else assoc key l
   | [] -> raise Not_found;;
val assoc : 'a -> ('a * 'b) list -> 'b = <fun>

# assoc 2 l;;
- : string = "World"

# assoc 3 l;;
- Exception: Not_found.

# "Hello" ^ assoc 2 l;;
- : string = "HelloWorld"
let find_index p =
    let rec find n =
        function [] -> raise (Failure "not found")
            | x::L -> if p(x) then raise (Found n)
                else find (n+1) L
        in
        try find 1 L with Found n ->  n;;