



# Recap on Subtyping



# Subsumption

Some types *are better* than others, in the sense that a value of one can *always safely be used* where a value of the other is expected.

Which can be formalized as by introducing:

1. a *subtyping* relation between types, written  $S <: T$
2. a *rule of subsumption* stating that, if  $S <: T$ , then any value of type  $S$  can also be regarded as having type  $T$

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$

*Principle of safe substitution*



*Syntax*

$t ::=$

- $x$  *terms:*  
*variable*
- $\lambda x:T. t$  *abstraction*
- $t t$  *application*

$v ::=$

- $\lambda x:T. t$  *values:*  
*abstraction value*

$T ::=$

- Top *types:*  
*maximum type*
- $T \rightarrow T$  *type of functions*

$\Gamma ::=$

- $\emptyset$  *contexts:*  
*empty context*
- $\Gamma, x:T$  *term variable binding*

*Evaluation*

$$\boxed{t \rightarrow t'}$$

$$\frac{t_1 \rightarrow t'_1}{t_1 t_2 \rightarrow t'_1 t_2} \quad (\text{E-APP1})$$

$$\frac{t_2 \rightarrow t'_2}{v_1 t_2 \rightarrow v_1 t'_2} \quad (\text{E-APP2})$$

$$(\lambda x:T_{11}. t_{12}) v_2 \rightarrow [x \mapsto v_2] t_{12} \quad (\text{E-APPABS})$$

*Subtyping*

$$\boxed{S <: T}$$

$$S <: S$$

(S-REFL)

$$\frac{S <: U \quad U <: T}{S <: T}$$

(S-TRANS)

$$S <: \text{Top}$$

(S-TOP)

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2}$$

(S-ARROW)

*Typing*

$$\boxed{\Gamma \vdash t : T}$$

$$\frac{x:T \in \Gamma}{\Gamma \vdash x : T}$$

(T-VAR)

$$\frac{\Gamma, x:T_1 \vdash t_2 : T_2}{\Gamma \vdash \lambda x:T_1. t_2 : T_1 \rightarrow T_2}$$

(T-ABS)

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 t_2 : T_{12}}$$

(T-APP)

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T}$$

(T-SUB)

# Records



$\rightarrow \{\}$

Extends  $\lambda_{\rightarrow}$  (9-1)

*New syntactic forms*

$t ::= \dots$   
 $\{\lambda_i = t_i \mid i \in 1..n\}$   
 $t.l$

*terms:*  
*record*  
*projection*

$v ::= \dots$   
 $\{\lambda_i = v_i \mid i \in 1..n\}$

*values:*  
*record value*

$T ::= \dots$   
 $\{\lambda_i : T_i \mid i \in 1..n\}$

*types:*  
*type of records*

*New evaluation rules*

$\{\lambda_i = v_i \mid i \in 1..n\}.l_j \rightarrow v_j$

$t \rightarrow t'$   
 (E-PROJRCD)

$$\frac{t_1 \rightarrow t'_1}{t_1.l \rightarrow t'_1.l} \quad \text{(E-PROJ)}$$

$$\frac{t_j \rightarrow t'_j}{\{\lambda_i = v_i \mid i \in 1..j-1, \lambda_j = t_j, \lambda_k = t_k \mid k \in j+1..n\} \rightarrow \{\lambda_i = v_i \mid i \in 1..j-1, \lambda_j = t'_j, \lambda_k = t_k \mid k \in j+1..n\}} \quad \text{(E-RCD)}$$

*New typing rules*

$\Gamma \vdash t : T$

$$\frac{\text{for each } i \quad \Gamma \vdash t_i : T_i}{\Gamma \vdash \{\lambda_i = t_i \mid i \in 1..n\} : \{\lambda_i : T_i \mid i \in 1..n\}} \quad \text{(T-RCD)}$$

$$\frac{\Gamma \vdash t_1 : \{\lambda_i : T_i \mid i \in 1..n\}}{\Gamma \vdash t_1.l_j : T_j} \quad \text{(T-PROJ)}$$

# Records & Subtyping



→  $\{\}$   $<$

Extends  $\lambda_{<}$  (15-1) and simple record rules (15-2)

New subtyping rules

$S <: T$

$\{\lceil_i : T_i^{i \in 1..n+k}\rceil <: \{\lceil_i : T_i^{i \in 1..n}\rceil$  (S-RCDWIDTH)

$\frac{\text{for each } i \quad S_i <: T_i}{\{\lceil_i : S_i^{i \in 1..n}\rceil <: \{\lceil_i : T_i^{i \in 1..n}\rceil}$  (S-RCDDEPTH)

$\{\lceil_j : S_j^{j \in 1..n}\rceil$  is a permutation of  $\{\lceil_i : T_i^{i \in 1..n}\rceil$

$\{\lceil_j : S_j^{j \in 1..n}\rceil <: \{\lceil_i : T_i^{i \in 1..n}\rceil$

(S-RCDPERM)



# Properties of Subtyping

# Safety



*Do the Statements of progress and preservation theorems need change?*

*Statements of progress and preservation theorems are unchanged from  $\lambda_{\rightarrow}$ .*



# Safety



Statements of **progress** and **preservation** theorems are unchanged from  $\lambda_{\rightarrow}$ .

*However*, Proofs become a bit *more involved*, because the typing relation is no longer *syntax directed*.

Given a derivation, *we don't always know what rule was used* in the last step.

e.g., the rule **T-SUB** could appear anywhere.

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$



# Syntax-directed rules

When we say a set of rules is syntax-directed we mean two things:

1. There is *exactly one rule* in the set that applies to each syntactic form. (We can tell by the syntax of a term which rule to use.)
  - In order to derive a type for  $t_1 t_2$ , we must use **T-App**.
2. We don't have to “*guess*” an input (or output) for any rule.
  - To derive a type for  $t_1 t_2$ , we need to derive a type for  $t_1$  and a type for  $t_2$ .

# Preservation



*Theorem: If  $\Gamma \vdash t : T$  and  $t \rightarrow t'$ , then  $\Gamma \vdash t' : T$ .*

*Proof: By induction on **typing derivations**.*

*Which cases are likely to be **hard**?*



# Subsumption case

Case T-Sub:  $t : S \quad S <: T$

By the induction hypothesis,  $\Gamma \vdash t' : S$ .

By T-Sub,  $\Gamma \vdash t' : T$ .

Not hard!



# Application case

Case **T-App** :

$$t = t_1 t_2 \quad \Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11} \quad T = T_{12}$$

By the inversion lemma for evaluation, there are *three rules* by which  $t \rightarrow t'$  can be derived:

E-App1, E-App2, and E-AppAbs .

Proceed by cases.



# Application case

Case **T-App** :

$$t = t_1 t_2 \quad \Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11} \quad T = T_{12}$$

By the evaluation rules in Figure 15-1 and 15-2, there are *three rules* by which  $t \rightarrow t'$  can be derived:

**E-App1**, **E-App2**, and **E-AppAbs**.

Proceed by cases.

Subcase **E-App1**:  $t_1 \rightarrow t'_1 \quad t' = t'_1 t_2$

The result follows from the induction hypothesis and **T-App**.

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 t_2 : T_{12}} \quad (\text{T-APP})$$

# Application case



Case **T-App**:

$$t = t_1 t_2 \quad \Gamma \vdash t_1 : T_{11} \longrightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11} \quad T = T_{12}$$

*Subcase E-App2*:  $t_1 = v_1 \quad t_2 \longrightarrow t'_2 \quad t' = v_1 t'_2$

Similar.

$$\frac{\Gamma \vdash t_1 : T_{11} \longrightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 t_2 : T_{12}} \quad (\text{T-APP})$$

$$\frac{t_2 \longrightarrow t'_2}{v_1 t_2 \longrightarrow v_1 t'_2} \quad (\text{E-APP2})$$

# Application case

Case **T-App**:

$$t = t_1 t_2 \quad \Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11} \quad T = T_{12}$$

Subcase **E-AppAbs**:

$$t_1 = \lambda x : S_{11}. t_{12} \quad t_2 = v_2 \quad t' = [x \mapsto v_2] t_{12}$$

by the *inversion lemma* for the typing relation ...

$$T_{11} <: S_{11} \quad \text{and} \quad \Gamma, x : S_{11} \vdash t_{12} : T_{12} .$$

By using **T-Sub**,  $\Gamma \vdash t_2 : S_{11}$ .

by the *substitution lemma*,  $\Gamma \vdash t' : T_{12}$ .

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 t_2 : T_{12}} \quad (\text{T-APP})$$

$$(\lambda x : T_{11}. t_{12}) v_2 \longrightarrow [x \mapsto v_2] t_{12} \quad (\text{E-APPABS})$$





# Inversion Lemma for Typing

*Lemma(15.3.3):* If  $\Gamma \vdash \lambda x:S_1. s_2: T_1 \rightarrow T_2$ , then  
 $T_1 <: S_1$  and  $\Gamma, x:S_1 \vdash s_2: T_2$ .

*Proof: Induction on typing derivations.*

*Case T-Sub:*  $\lambda x:S_1. s_2: U$       $U: T_1 \rightarrow T_2$

We want to say “By the induction hypothesis...”, but the IH does not apply ( since we do not know that  $U$  is an arrow type).

Need another lemma...

*Lemma (15.3.2):* If  $U <: T_1 \rightarrow T_2$ , then  $U$  has the form of  
 $U_1 \rightarrow U_2$ ,

with  $T_1 <: U_1$  and  $U_2 <: T_2$ .

(*Proof:* by *induction on subtyping derivations.*)



# Inversion Lemma for Typing

By **this lemma**, we know

$$U = U_1 \longrightarrow U_2, \text{ with } T_1 <: U_1 \text{ and } U_2 <: T_2.$$

The **IH** now applies, yielding

$$U_1 <: S_1 \text{ and } \Gamma, x: S_1 \vdash s_2: U_2.$$

From  $U_1 <: S_1$  and  $T_1 <: U_1$ , rule **S-Trans** gives

$$T_1 <: S_1.$$

From  $\Gamma, x: S_1 \vdash s_2: U_2$  and  $U_2 <: T_2$ , rule **T-Sub** gives

$$\Gamma, x: S_1 \vdash s_2: T_2,$$

and we are done.

# Progress



*Theorem: If  $t$  is a closed, well-typed term, then either  $t$  is a value or else there is some  $t'$ , with and  $t \rightarrow t'$*

*Proof: By induction on **typing derivations**.*

*Which cases are likely to be hard?*

case T-APP

case T-RCD

case T-PROJ

case T-SUB



# Subtyping with Other Features

# Ascription and Casting



Ordinary ascription:

$$\frac{\Gamma \vdash t_1 : T}{\Gamma \vdash t_1 \text{ as } T : T} \quad (\text{T-ASCRIIBE})$$

$$v_1 \text{ as } T \longrightarrow v_1 \quad (\text{E-ASCRIIBE})$$

# Ascription and Casting



Ordinary ascription:

$$\frac{\Gamma \vdash t_1 : T}{\Gamma \vdash t_1 \text{ as } T : T} \quad (\text{T-ASCRIIBE})$$

$$v_1 \text{ as } T \longrightarrow v_1 \quad (\text{E-ASCRIIBE})$$

Casting (cf. Java):

$$\frac{\Gamma \vdash t_1 : S}{\Gamma \vdash t_1 \text{ as } T : T} \quad (\text{T-CAST})$$

$$\frac{\vdash v_1 : T}{v_1 \text{ as } T \longrightarrow v_1} \quad (\text{E-CAST})$$

# Subtyping and Variants



$$\langle l_i : T_i \rangle_{i \in 1..n} <: \langle l_i : T_i \rangle_{i \in 1..n+k} \quad (\text{S-VARIANTWIDTH})$$

$$\frac{\text{for each } i \quad S_i <: T_i}{\langle l_i : S_i \rangle_{i \in 1..n} <: \langle l_i : T_i \rangle_{i \in 1..n}} \quad (\text{S-VARIANTDEPTH})$$

$$\frac{\langle k_j : S_j \rangle_{j \in 1..n} \text{ is a permutation of } \langle l_i : T_i \rangle_{i \in 1..n}}{\langle k_j : S_j \rangle_{j \in 1..n} <: \langle l_i : T_i \rangle_{i \in 1..n}} \quad (\text{S-VARIANTPERM})$$

$$\frac{\Gamma \vdash t_1 : T_1}{\Gamma \vdash \langle l_1 = t_1 \rangle : \langle l_1 : T_1 \rangle} \quad (\text{T-VARIANT})$$

# Subtyping and Lists



$$\frac{S_1 <: T_1}{\text{List } S_1 <: \text{List } T_1} \quad (\text{S-LIST})$$

i.e., List is a covariant type constructor.



# Subtyping and References



$$\frac{S_1 <: T_1 \quad T_1 <: S_1}{\text{Ref } S_1 <: \text{Ref } T_1} \quad (\text{S-REF})$$

i.e., **Ref** is not a *covariant* (nor a *contravariant*) type constructor.

# Subtyping and References



$$\frac{S_1 <: T_1 \quad T_1 <: S_1}{\text{Ref } S_1 <: \text{Ref } T_1} \quad (\text{S-REF})$$

i.e., **Ref** is not a *covariant* (nor a *contravariant*) type constructor.

Why?

- When a reference is *read*, the context expects a  $T_1$ , so if  $S_1 <: T_1$  then an  $S_1$  is ok.

# Subtyping and References



$$\frac{S_1 <: T_1 \quad T_1 <: S_1}{\text{Ref } S_1 <: \text{Ref } T_1} \quad (\text{S-REF})$$

i.e., **Ref** is not a *covariant* (nor a *contravariant*) type constructor.

Why?

- When a reference is *read*, the context expects a  $T_1$ , so if  $S_1 <: T_1$  then an  $S_1$  is ok.
- When a reference is *written*, the context provides a  $T_1$  and if the actual type of the reference is  $\text{Ref } S_1$ , someone else may use the  $T_1$  as an  $S_1$ . So we need  $T_1 <: S_1$ .

# References again



Observation: a value of type **Ref T** can be used in two different ways: as a *source* for values of type **T** and as a *sink* for values of type **T**.

Idea: Split **Ref T** into three parts:

- **Source T**: reference cell with “read capability”
- **Sink T**: reference cell with “write capability”
- **Ref T**: cell with both capabilities

# Subtyping and Arrays



Similarly...

$$\frac{S_1 <: T_1 \quad T_1 <: S_1}{\text{Array } S_1 <: \text{Array } T_1} \quad (\text{S-ARRAY})$$

$$\frac{S_1 <: T_1}{\text{Array } S_1 <: \text{Array } T_1} \quad (\text{S-ARRAYJAVA})$$

This is regarded (even by the Java designers) as a mistake in the design.

# References again



Observation: a value of type *Ref T* can be used in two different ways:

- as a *source* for values of type **T**, and
- as a *sink* for values of type **T**.



# References again

Observation: a value of type *Ref T* can be used in two different ways:

- as a *source* for values of type **T**, and
- as a *sink* for values of type **T**.

Idea: Split *Ref T* into three parts:

- **Source T**: reference cell with “read capability”
- **Sink T**: reference cell with “write capability”
- **Ref T**: cell with both capabilities

# Modified Typing Rules



$$\frac{\Gamma \mid \Sigma \vdash t_1 : \text{Source } T_{11}}{\Gamma \mid \Sigma \vdash !t_1 : T_{11}} \quad (\text{T-DEREF})$$

$$\frac{\Gamma \mid \Sigma \vdash t_1 : \text{Sink } T_{11} \quad \Gamma \mid \Sigma \vdash t_2 : T_{11}}{\Gamma \mid \Sigma \vdash t_1 := t_2 : \text{Unit}} \quad (\text{T-ASSIGN})$$



# Subtyping rules



$$\frac{S_1 <: T_1}{\text{Source } S_1 <: \text{Source } T_1} \quad (\text{S-SOURCE})$$

$$\frac{T_1 <: S_1}{\text{Sink } S_1 <: \text{Sink } T_1} \quad (\text{S-SINK})$$

$$\text{Ref } T_1 <: \text{Source } T_1 \quad (\text{S-REFSOURCE})$$

$$\text{Ref } T_1 <: \text{Sink } T_1 \quad (\text{S-REFSINK})$$

# Capabilities



Other kinds of capabilities can be treated similarly, e.g.,

- send and receive capabilities on communication channels,
- encrypt/decrypt capabilities of cryptographic keys,
- ...



# Intersection and Union Types

# Intersection Types

The inhabitants of  $T_1 \wedge T_2$  are terms belonging to *both*  $S$  and  $T$  —i.e.,  $T_1 \wedge T_2$  is an order-theoretic meet (greatest lower bound) of  $T_1$  and  $T_2$ .

$$T_1 \wedge T_2 <: T_1$$

(S-INTER1)

$$T_1 \wedge T_2 <: T_2$$

(S-INTER2)

$$\frac{S <: T_1 \quad S <: T_2}{S <: T_1 \wedge T_2}$$

(S-INTER3)

$$S \rightarrow T_1 \wedge S \rightarrow T_2 <: S \rightarrow (T_1 \wedge T_2)$$

(S-INTER4)



# Intersection Types

Intersection types permit a very *flexible form* of *finitary overloading*.

$$+ : (\text{Nat} \rightarrow \text{Nat} \rightarrow \text{Nat}) \wedge (\text{Float} \rightarrow \text{Float} \rightarrow \text{Float})$$

This form of overloading is extremely powerful.

Every strongly normalizing untyped lambda-term can be typed in the simply typed lambda-calculus with intersection types.

type reconstruction problem is undecidable

Intersection types *have not been used much* in language designs (too powerful!), but are being *intensively investigated* as type systems for *intermediate languages* in highly optimizing compilers (cf. Church project).



# Union types

Union types are also useful.

$T_1 \vee T_2$  is an **untagged** (non-disjoint) union of  $T_1$  and  $T_2$ .

No tags : no *case* construct. The only operations we can safely perform on elements of  $T_1 \vee T_2$  are ones *that make sense for both*  $T_1$  and  $T_2$ .

**N. B:** untagged union types in C are a source of *type safety violations* precisely because they ignores this restriction, allowing any operation on an element of  $T_1 \vee T_2$  that makes sense for *either*  $T_1$  or  $T_2$ .

Union types are being used recently in type systems for XML processing languages (cf. Xduce, Xtatic).

# Varieties of Polymorphism



- Parametric polymorphism (ML-style)
- Subtype polymorphism (OO-style)
- Ad-hoc polymorphism (overloading)



# Chap 16

# Metatheory of Subtyping

Algorithmic Subtyping

Algorithmic Typing

Joins and Meets





# Developing an algorithmic subtyping relation

# Subtype Relation



$$S <: S \quad (\text{S-REFL})$$

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

$$\{l_j : T_j^{i \in 1..n+k}\} <: \{l_j : T_j^{i \in 1..n}\} \quad (\text{S-RCDWIDTH})$$

$$\frac{\text{for each } i \quad S_i <: T_i}{\{l_j : S_j^{i \in 1..n}\} <: \{l_j : T_j^{i \in 1..n}\}} \quad (\text{S-RCDDEPTH})$$

$$\frac{\{k_j : S_j^{j \in 1..n}\} \text{ is a permutation of } \{l_j : T_j^{i \in 1..n}\}}{\{k_j : S_j^{j \in 1..n}\} <: \{l_j : T_j^{i \in 1..n}\}} \quad (\text{S-RCDPERM})$$

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{S-ARROW})$$

$$S <: \text{Top} \quad (\text{S-TOP})$$



# Issues in Subtyping

For a *given subtyping statement*, there are *multiple rules* that could be used in a derivation.

1. The conclusions of **S-RcdWidth**, **S-RcdDepth**, and **S-RcdPerm** *overlap with each other*.
2. **S-REFL** and **S-TRANS** overlap with every other rule.



# What to do?

We'll turn the *declarative version* of subtyping into the *algorithmic version*.

The **problem** was that we don't have an algorithm to decide when  $S <: T$  or  $\Gamma \vdash t : T$ .

Both sets of rules are not *syntax-directed*.



# Syntax-directed rules

In the simply typed lambda-calculus (without subtyping), each rule can be “*read from bottom to top*” in a straightforward way.

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 t_2 : T_{12}} \quad (\text{T-APP})$$

# Syntax-directed rules

In the simply typed lambda-calculus (without subtyping), each rule can be “*read from bottom to top*” in a straightforward way.

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 t_2 : T_{12}} \quad (\text{T-APP})$$

If we are given some  $\Gamma$  and some  $t$  of the form  $t_1 t_2$ , we can try to *find a type* for  $t$  by

1. finding (recursively) a type for  $t_1$
2. checking that it has the form  $T_{11} \rightarrow T_{12}$
3. finding (recursively) a type for  $t_2$
4. checking that it is the same as  $T_{11}$



# Syntax-directed rules

Technically, the reason this works is that we can *divide the “positions”* of the typing relation into *input positions* (i.e.,  $\Gamma$  and  $t$ ) and *output positions* ( $T$ ).

- For the input positions, all metavariables appearing in the *premises* also appear in the *conclusion* (so we can calculate inputs to the “subgoals” from the subexpressions of inputs to the main goal)
- For the output positions, all metavariables appearing in the *conclusions* also appear in the *premises* (so we can calculate outputs from the main goal from the outputs of the subgoals)

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 \ t_2 : T_{12}} \quad (\text{T-APP})$$

# Syntax-directed sets of rules



The *second important point* about the simply typed lambda-calculus is that *the set of typing rules is syntax-directed*, in the sense that, for every “*input*”  $\Gamma$  and  $t$ , *there is one rule* that can be used to derive typing statements involving  $t$ .

E.g., if  $t$  is an *application*, then we must proceed by trying to use **T-App**. If we succeed, then we have found a type (indeed, the *unique type*) for  $t$ . If it *fails*, then we know that  $t$  is *not typable*.

⇒ no backtracking!



# Non-syntax-directedness of typing



When we extend the system with *subtyping*, both aspects of syntax-directedness get broken.

1. The set of typing rules now includes *two* rules that can be used to give a type to terms of a given shape (the old one plus T-SUB)

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$

2. Worse yet, the new rule T-SUB itself is not syntax directed: the *inputs* to the left-hand subgoal are exactly the same as the *inputs* to the main goal!

(Hence, if we translated the typing rules naively into a typechecking function, the case corresponding to T-SUB would cause divergence.)

# Non-syntax-directedness of subtyping



Moreover, the *subtyping relation* is *not syntax directed* either.

1. There are *lots* of ways to derive a given subtyping statement.
2. The transitivity rule

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

is *badly non-syntax-directed*: the premises contain a *metavariable* (in an “*input position*”) that does *not appear at all in the conclusion*.

To implement this rule naively, we have to *guess* a value for *U*!



# What to do?

1. *Observation*: We don't *need* lots of ways to prove a given typing or subtyping statement — *one is enough*.  
→ Think more carefully about the *typing and subtyping systems* to see where we can get rid of excess flexibility
2. Use the resulting intuitions to formulate new “*algorithmic*” (i.e., syntax-directed) typing and subtyping relations.
3. Prove that the algorithmic relations are “*the same as*” the original ones in an appropriate sense.



# Algorithmic Subtyping



# What to do

How do we change the rules deriving  $S <: T$  to be *syntax-directed*?

There are lots of ways to derive a given subtyping statement  $S <: T$ .

The general idea is to change this system so that there is *only one way* to derive it.

# Step 1: simplify record subtyping



**Idea:** combine all three record subtyping rules into one “*macro rule*” that captures all of their effects

$$\frac{\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad k_j = l_i \text{ implies } S_j <: T_i}{\{k_j : S_j^{j \in 1..m}\} <: \{l_i : T_i^{i \in 1..n}\}} \quad (\text{S-RCD})$$

# Simpler subtype relation



$$S <: S \quad (\text{S-REFL})$$

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

$$\frac{\{l_j^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad k_j = l_j \text{ implies } S_j <: T_j}{\{k_j : S_j^{j \in 1..m}\} <: \{l_j : T_j^{i \in 1..n}\}} \quad (\text{S-RCD})$$

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{S-ARROW})$$

$$S <: \text{Top} \quad (\text{S-TOP})$$

# Step 2: Get rid of reflexivity



*Observation:* S-REFL is unnecessary.

*Lemma:*  $S <: S$  can be derived for every type  $S$  without using S-REFL.



# Even simpler subtype relation



$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

$$\frac{\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad k_j = l_i \text{ implies } S_j <: T_i}{\{k_j : S_j^{j \in 1..m}\} <: \{l_i : T_i^{i \in 1..n}\}} \quad (\text{S-RCD})$$

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{S-ARROW})$$

$$S <: \text{Top} \quad (\text{S-TOP})$$

# Step 3: Get rid of transitivity



*Observation:* S-Trans is unnecessary.

*Lemma:* If  $S \leq T$  can be derived, then it can be derived without using S-Trans .

# “Algorithmic” subtype relation



$\boxed{\vdash} S <: \text{Top}$

$(\boxed{\text{SA-}}\text{TOP})$

$$\frac{\vdash T_1 <: S_1 \quad \vdash S_2 <: T_2}{\vdash S_1 \rightarrow S_2 <: T_1 \rightarrow T_2}$$

$(\text{SA-ARROW})$

$$\frac{\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad \text{for each } k_j = l_i, \vdash S_j <: T_i}{\vdash \{k_j : S_j^{j \in 1..m}\} <: \{l_i : T_i^{i \in 1..n}\}}$$

$(\text{SA-RCD})$

# Soundness and completeness



*Theorem:*  $S <: T$  iff  $\mapsto S <: T$

## Terminology:

- The algorithmic presentation of subtyping is *sound* with respect to the original if  $\mapsto S <: T$  implies  $S <: T$ . (Everything validated by the algorithm is actually true.)
- The algorithmic presentation of subtyping is *complete* with respect to the original if  $S <: T$  implies  $\mapsto S <: T$ . (Everything true is validated by the algorithm.)



# Decision Procedures

A *decision procedure* for a relation  $R \subseteq U$  is a *total function*  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .

# Decision Procedures



*Recall: A decision procedure for a relation  $R \subseteq U$  is a total function  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .*

Is our *subtype* function a decision procedure?

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Is our *subtype* function a decision procedure?

Since *subtype* is just an implementation of the algorithmic subtyping rules, we have

1. if  $subtype(S, T) = true$ , then  $\mapsto S <: T$  (hence, by **soundness** of the algorithmic rules,  $S <: T$ )
2. if  $subtype(S, T) = false$ , then not  $\mapsto S <: T$  (hence, by **completeness** of the algorithmic rules, not  $S <: T$ )

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Q: What's missing?



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Q: What's missing?

A: How do we know that *subtype* is a **total function**?



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Q: What's missing?

A: How do we know that *subtype* is a total function?

Prove it!



# Decision Procedures

Recall: A decision procedure for a relation  $R \subseteq U$  is *a total function*  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .

Example:

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

**Note that**, we are saying nothing about *computability*.

# Decision Procedures



*Recall:* A decision procedure for a relation  $R \subseteq U$  is *a total function*  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .

Example:

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The function  $p$  whose graph is

$$\begin{aligned} &\{ ((1, 2), true), ((2, 3), true), \\ &\quad ((1, 1), false), ((1, 3), false), \\ &\quad ((2, 1), false), ((2, 2), false), \\ &\quad ((3, 1), false), ((3, 2), false), ((3, 3), false) \} \end{aligned}$$

is a decision function for  $R$ .



# Decision Procedures

Recall: A decision procedure for a relation  $R \subseteq U$  is *a total function*  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .

Example:

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The function  $p'$  whose graph is

$$\{((1, 2), true), ((2, 3), true)\}$$

*is not* a decision function for  $R$ .



# Decision Procedures

Recall: A decision procedure for a relation  $R \subseteq U$  is *a total function*  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .

Example:

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The function  $p''$  whose graph is

$$\{((1, 2), true), ((2, 3), true), ((1, 3), false)\}$$

is *also not* a decision function for  $R$ .

# Decision Procedures (take 2)



We want a decision procedure to be a *procedure*.

A *decision procedure* for a relation  $R \subseteq U$  is a *computable total function*  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .

# Example



$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The function

$$p(x, y) = \begin{array}{l} \text{if } x = 2 \text{ and } y = 3 \text{ then true} \\ \text{else if } x = 1 \text{ and } y = 2 \text{ then true} \\ \text{else false} \end{array}$$

whose graph is

$$\begin{array}{l} \{ ((1, 2), \text{true}), ((2, 3), \text{true}), \\ ((1, 1), \text{false}), ((1, 3), \text{false}), \\ ((2, 1), \text{false}), ((2, 2), \text{false}), \\ ((3, 1), \text{false}), ((3, 2), \text{false}), ((3, 3), \text{false}) \} \end{array}$$

is a decision procedure for  $R$ .





# Example

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The recursively defined *partial function*

$p(x, y) =$  if  $x = 2$  and  $y = 3$  then true  
else if  $x = 1$  and  $y = 2$  then true  
else if  $x = 1$  and  $y = 3$  then false  
else  $p(x, y)$

# Example



$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The recursively defined *partial function*

$$\begin{aligned} p(x, y) = & \text{if } x = 2 \text{ and } y = 3 \text{ then true} \\ & \text{else if } x = 1 \text{ and } y = 2 \text{ then true} \\ & \text{else if } x = 1 \text{ and } y = 3 \text{ then false} \\ & \text{else } p(x, y) \end{aligned}$$

whose graph is

$$\{((1, 2), \text{true}), ((2, 3), \text{true}), ((1, 3), \text{false})\}$$

is *not* a decision procedure for  $R$ .

# Subtyping Algorithm



This *recursively defined total function* is a decision procedure for the subtype relation:

$subtype(S, T) =$

if  $T = \text{Top}$ , then *true*

else if  $S = S_1 \rightarrow S_2$  and  $T = T_1 \rightarrow T_2$

then  $subtype(T_1, S_1) \wedge subtype(S_2, T_2)$

else if  $S = \{k_j: S_j^{j \in 1..m}\}$  and  $T = \{l_i: T_i^{i \in 1..n}\}$

then  $\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\}$

$\wedge$  for all  $i \in 1..n$  there is some  $j \in 1..m$  with  $k_j = l_i$   
and  $subtype(S_j, T_i)$

else *false*.



# Subtyping Algorithm

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else if  $S = \{k_j: S_j^{j \in 1..m}\}$  and  $T = \{l_i: T_i^{i \in 1..n}\}$

then  $\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\}$

$\wedge$  for all  $i \in 1..n$  there is some  $j \in 1..m$  with  $k_j = l_i$   
and  $subtype(S_j, T_i)$

else *false*.

To show this, we need to prove:

1. that it returns *true* whenever  $S <: T$ , and
2. that it returns either *true* or *false* on all inputs.



# Algorithmic Typing

# Algorithmic typing



How do we implement a *type checker* for the lambda-calculus *with subtyping*?

Given a context  $\Gamma$  and a term  $t$ , how do we determine its type  $T$ , such that  $\Gamma \vdash t : T$ ?

# Issue



For the typing relation, we have *just one problematic rule* to deal with: subsumption rule

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$

Q: where is this rule really needed?

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Q: where is this rule really needed?

For applications, e.g., the term

$$(\lambda r: \{x: \text{Nat}\}. r. x) \{x = 0, y = 1\}$$

is *not typable* without using subsumption.



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Where else??

# Issue



For the typing relation, we have *just one problematic rule* to deal with: subsumption

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Q: where is this rule really needed?

For *applications*, e.g., the term

$(\lambda r: \{x: \text{Nat}\}. r. x) \{x = 0, y = 1\}$

is *not typable* without using subsumption.

Where else??

*Nowhere else!*

Uses of subsumption to help typecheck *applications* are the only interesting ones.

# Plan



1. Investigate *how subsumption is used in typing derivations* by *looking at examples* of how it can be “pushed through” other rules
2. Use the intuitions gained from this exercise to design a new, algorithmic typing relation that
  - *Omits subsumption*
  - Compensates for its absence by *enriching the application rule*
3. *Show that* the algorithmic typing relation is essentially *equivalent* to the original, declarative one

# Example (T-ABS)



$$\frac{\frac{\vdots}{\Gamma, x:S_1 \vdash s_2 : S_2} \quad \frac{\vdots}{S_2 <: T_2}}{\Gamma, x:S_1 \vdash s_2 : T_2} \text{ (T-SUB)}}{\Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow T_2} \text{ (T-ABS)}$$

# Example (T-ABS)



$$\begin{array}{c}
 \vdots \qquad \qquad \qquad \vdots \\
 \hline
 \Gamma, x:S_1 \vdash s_2 : S_2 \qquad S_2 <: T_2 \\
 \hline
 \Gamma, x:S_1 \vdash s_2 : T_2 \quad (\text{T-SUB}) \\
 \hline
 \Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow T_2 \quad (\text{T-ABS})
 \end{array}$$

becomes

$$\begin{array}{c}
 \vdots \qquad \qquad \qquad \vdots \\
 \hline
 \Gamma, x:S_1 \vdash s_2 : S_2 \qquad S_1 <: S_1 \quad (\text{S-REFL}) \qquad S_2 <: T_2 \\
 \hline
 \Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow S_2 \quad (\text{T-ABS}) \qquad S_1 \rightarrow S_2 <: S_1 \rightarrow T_2 \quad (\text{S-ARROW}) \\
 \hline
 \Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow T_2 \quad (\text{T-SUB})
 \end{array}$$

# Intuitions



These examples show that we do not need **T-SUB** to “enable” **T-ABS** : given any typing derivation, we can construct a derivation *with the same conclusion* in which **T-SUB** is never used immediately before **T-ABS**.

What about **T-APP**?

We’ve already observed that **T-SUB** is required for typechecking some *applications*. So we expect to find that we *cannot* play the same game with **T-APP** as we’ve done with **T-ABS**.

Let’s see why.

# Example (T-Sub with T-APP on the left)



$$\begin{array}{c}
 \vdots \\
 \hline
 \Gamma \vdash s_1 : S_{11} \rightarrow S_{12} \\
 \hline
 \Gamma \vdash s_1 : T_{11} \rightarrow T_{12} \quad \text{(T-SUB)} \\
 \hline
 \Gamma \vdash s_1 s_2 : T_{12} \quad \text{(T-APP)} \\
 \hline
 \Gamma \vdash s_1 s_2 : T_{12}
 \end{array}
 \qquad
 \begin{array}{c}
 \vdots \\
 \hline
 \Gamma \vdash s_2 : T_{11} \\
 \hline
 \Gamma \vdash s_2 : S_{11} \quad \text{(T-SUB)} \\
 \hline
 S_{12} <: T_{12} \quad \text{(T-SUB)} \\
 \hline
 \Gamma \vdash s_1 s_2 : T_{12}
 \end{array}$$

becomes

$$\begin{array}{c}
 \vdots \\
 \hline
 \Gamma \vdash s_1 : S_{11} \rightarrow S_{12} \\
 \hline
 \Gamma \vdash s_1 s_2 : S_{12} \quad \text{(T-APP)} \\
 \hline
 \Gamma \vdash s_1 s_2 : T_{12} \quad \text{(T-SUB)}
 \end{array}
 \qquad
 \begin{array}{c}
 \vdots \\
 \hline
 \Gamma \vdash s_2 : T_{11} \\
 \hline
 \Gamma \vdash s_2 : S_{11} \quad \text{(T-SUB)} \\
 \hline
 S_{12} <: T_{12} \quad \text{(T-SUB)} \\
 \hline
 \Gamma \vdash s_1 s_2 : T_{12}
 \end{array}$$

# Example (T-Sub with T-APP on the right)



$$\frac{\frac{\vdots}{\Gamma \vdash s_1 : T_{11} \rightarrow T_{12}} \quad \frac{\frac{\vdots}{\Gamma \vdash s_2 : T_2} \quad T_2 <: T_{11}}{\Gamma \vdash s_2 : T_{11}} \text{ (T-SUB)}}{\Gamma \vdash s_1 s_2 : T_{12}} \text{ (T-APP)}$$

becomes

$$\frac{\frac{\frac{\vdots}{\Gamma \vdash s_1 : T_{11} \rightarrow T_{12}} \quad \frac{\frac{\vdots}{T_2 <: T_{11}} \quad T_{12} <: T_{12}}{T_{11} \rightarrow T_{12} <: T_2 \rightarrow T_{12}} \text{ (S-REFL) (S-ARROW)}}{\Gamma \vdash s_1 : T_2 \rightarrow T_{12}} \text{ (T-SUB)} \quad \frac{\vdots}{\Gamma \vdash s_2 : T_2}}{\Gamma \vdash s_1 s_2 : T_{12}} \text{ (T-APP)}$$





# Observations

---

So we've seen that uses of subsumption can be “*pushed*” from one of immediately before **T-APP**'s premises to the other, but *cannot be completely eliminated*.

# Example (nested uses of T-Sub)



$$\frac{\frac{\frac{\vdots}{\Gamma \vdash s : S} \quad \frac{\frac{\vdots}{S <: U}}{\Gamma \vdash s : U} \text{ (T-SUB)}}{\Gamma \vdash s : U} \quad \frac{\frac{\vdots}{U <: T}}{\Gamma \vdash s : T} \text{ (T-SUB)}}{\Gamma \vdash s : T} \text{ (T-SUB)}$$

# Example (nested uses of T-Sub)



$$\frac{\frac{\frac{\vdots}{\Gamma \vdash s : S} \quad \frac{\frac{\vdots}{S <: U}}{\Gamma \vdash s : U} \text{ (T-SUB)}}{\Gamma \vdash s : U} \quad \frac{\frac{\vdots}{U <: T}}{\Gamma \vdash s : T} \text{ (T-SUB)}}{\Gamma \vdash s : T} \text{ (T-SUB)}$$

becomes

$$\frac{\frac{\frac{\vdots}{\Gamma \vdash s : S} \quad \frac{\frac{\frac{\vdots}{S <: U} \quad \frac{\frac{\vdots}{U <: T}}{S <: T} \text{ (S-TRANS)}}{\Gamma \vdash s : S} \quad S <: T}{\Gamma \vdash s : T} \text{ (T-SUB)}}{\Gamma \vdash s : T} \text{ (T-SUB)}$$

# Summary



## What we've learned:

- Uses of the **T-Sub** rule can be “*pushed down*” through typing derivations until they encounter either
  1. a use of **T-App** or
  2. the root of the derivation tree.
- In both cases, multiple uses of **T-Sub** can be coalesced into a single one.

# Summary



## What we've learned:

- Uses of the T-Sub rule can be “pushed down” through typing derivations until they encounter either
  1. a use of T-App or
  2. the root of the derivation tree.
- In both cases, multiple uses of T-Sub can be collapsed into a single one.

This suggests a notion of “normal form” for typing derivations, in which there is

- exactly one use of T-Sub before each use of T-App
- one use of T-Sub at the very end of the derivation
- no uses of T T-Sub anywhere else.

# Algorithmic Typing



The next step is to “build in” the use of subsumption in application rules, by changing the **T-App** rule to incorporate a subtyping premise.

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_2 \quad \vdash T_2 <: T_{11}}{\Gamma \vdash t_1 t_2 : T_{12}}$$

Given any typing derivation, we can now

1. **normalize** it, to move all uses of subsumption to either just before applications (in the right-hand premise) or at the very end
2. **replace** uses of **T-App** with **T-SUB** in the right-hand premise by uses of the extended rule above

This yields a derivation in which there is just *one* use of subsumption, at the very end!

# Minimal Types



But... if subsumption is only used at the very end of derivations, then it is actually *not needed* in order to show that *any term is typable*!

It is just used to give *more* types to terms that have already been shown to have a type.

In other words, if we dropped subsumption completely (after refining the application rule), we would still be able to give types to exactly the same set of terms — we just would not be able to give as many types to some of them.

If we drop subsumption, then the remaining rules will assign a *unique, minimal* type to each typable term.

For purposes of building a typechecking algorithm, this is enough.

# Final Algorithmic Typing Rules



$$\frac{x:T \in \Gamma}{\Gamma \vdash x : T} \quad (\text{TA-VAR})$$

$$\frac{\Gamma, x:T_1 \vdash t_2 : T_2}{\Gamma \vdash \lambda x:T_1. t_2 : T_1 \rightarrow T_2} \quad (\text{TA-ABS})$$

$$\frac{\Gamma \vdash t_1 : T_1 \quad T_1 = T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_2 \quad \vdash T_2 <: T_{11}}{\Gamma \vdash t_1 t_2 : T_{12}} \quad (\text{TA-APP})$$

$$\frac{\text{for each } i \quad \Gamma \vdash t_i : T_i}{\Gamma \vdash \{l_1=t_1 \dots l_n=t_n\} : \{l_1:T_1 \dots l_n:T_n\}} \quad (\text{TA-RCD})$$

$$\frac{\Gamma \vdash t_1 : R_1 \quad R_1 = \{l_1:T_1 \dots l_n:T_n\}}{\Gamma \vdash t_1.l_i : T_i} \quad (\text{TA-PROJ})$$



# Completeness of the algorithmic rules



**Theorem [Minimal Typing]:** If  $\Gamma \vdash t : T$ , then  $\Gamma \mapsto t : S$  for some  $S <: T$ .

# Completeness of the algorithmic rules



**Theorem [Minimal Typing]:** If  $\Gamma \vdash t : T$ , then  $\Gamma \mapsto t : S$  for some  $S <: T$ .

Proof: Induction on *typing derivation*.

(N.b.: All the messing around with transforming derivations was just to build intuitions and *decide what algorithmic rules* to write down and *what property* to prove: the proof itself is a straightforward induction on typing derivations.)



# Meets and Joins



# Adding Booleans

Suppose we want to add *booleans* and *conditionals* to the language we have been discussing.

For the declarative presentation of the system, we just add in the appropriate syntactic forms, evaluation rules, and typing rules.

$$\begin{array}{l} \Gamma \vdash \text{true} : \text{Bool} \qquad \qquad \qquad (\text{T-TRUE}) \\ \Gamma \vdash \text{false} : \text{Bool} \qquad \qquad \qquad (\text{T-FALSE}) \\ \hline \frac{\Gamma \vdash t_1 : \text{Bool} \quad \Gamma \vdash t_2 : T \quad \Gamma \vdash t_3 : T}{\Gamma \vdash \text{if } t_1 \text{ then } t_2 \text{ else } t_3 : T} \qquad \qquad \qquad (\text{T-IF}) \end{array}$$

# A Problem with Conditional Expressions



For the algorithmic presentation of the system, however, we encounter a little difficulty.

What is the minimal type of

*if true then {x = true, y = false} else {x = true, z = true}*

?

# The Algorithmic Conditional Rule



More generally, we can use subsumption to give an expression

if  $t_1$  then  $t_2$  else  $t_3$

any type that is a possible type of both  $t_2$  and  $t_3$ .

So the *minimal* type of the conditional is the *least common supertype* (or *join*) of the minimal type of  $t_2$  and the minimal type of  $t_3$ .

$$\frac{\Gamma \vdash t_1 : \text{Bool} \quad \Gamma \vdash t_2 : T_2 \quad \Gamma \vdash t_3 : T_3}{\Gamma \vdash \text{if } t_1 \text{ then } t_2 \text{ else } t_3 : T_2 \vee T_3} \quad (\text{T-IF})$$

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So the *minimal* type of the conditional is the *least common supertype* (or *join*) of the minimal type of  $t_2$  and the minimal type of  $t_3$ .

$$\frac{\Gamma \vdash t_1 : \text{Bool} \quad \Gamma \vdash t_2 : T_2 \quad \Gamma \vdash t_3 : T_3}{\Gamma \vdash \text{if } t_1 \text{ then } t_2 \text{ else } t_3 : T_2 \vee T_3} \quad (\text{T-IF})$$

Q: Does such a type exist for every  $T_2$  and  $T_3$ ??

# Existence of Joins



**Theorem:** For every pair of types  $S$  and  $T$ , there is a type  $J$  such that

1.  $S <: J$
2.  $T <: J$
3. If  $K$  is a type such that  $S <: K$  and  $T <: K$ , then  $J <: K$ .

i.e.,  $J$  is the smallest type that is a supertype of both  $S$  and  $T$ .

How to prove it?



# Examples



What are the joins of the following pairs of types?

1.  $\{x: \text{Bool}, y: \text{Bool}\}$  and  $\{y: \text{Bool}, z: \text{Bool}\}$ ?
2.  $\{x: \text{Bool}\}$  and  $\{y: \text{Bool}\}$ ?
3.  $\{x: \{a: \text{Bool}, b: \text{Bool}\}\}$  and  $\{x: \{b: \text{Bool}, c: \text{Bool}\}, y: \text{Bool}\}$ ?
4.  $\{\}$  and  $\text{Bool}$ ?
5.  $\{x: \{\}\}$  and  $\{x: \text{Bool}\}$ ?
6.  $\text{Top} \rightarrow \{x: \text{Bool}\}$  and  $\text{Top} \rightarrow \{y: \text{Bool}\}$ ?
7.  $\{x: \text{Bool}\} \rightarrow \text{Top}$  and  $\{y: \text{Bool}\} \rightarrow \text{Top}$ ?

# Meets



To calculate joins of arrow types, we also need to be able to calculate meets (greatest lower bounds)!

Unlike joins, meets do not necessarily exist.

E.g.,  $\text{Bool} \rightarrow \text{Bool}$  and  $\{\}$  have no common subtypes, so they certainly don't have a greatest one!

However...

# Existence of Meets



**Theorem:** For every pair of types  $S$  and  $T$ , if there is any type  $N$  such that  $N \leq S$  and  $N \leq T$ , then there is a type  $M$  such that

1.  $M \leq S$
2.  $M \leq T$
3. If  $O$  is a type such that  $O \leq S$  and  $O \leq T$ , then  $O \leq M$ .

i.e.,  $M$  (when it exists) is the largest type that is a subtype of both  $S$  and  $T$ .



# Existence of Meets

**Theorem:** For every pair of types  $S$  and  $T$ , if there is any type  $N$  such that  $N <: S$  and  $N <: T$ , then there is a type  $M$  such that

1.  $M <: S$
2.  $M <: T$
3. If  $O$  is a type such that  $O <: S$  and  $O <: T$ , then  $O <: M$ .

i.e.,  $M$  (when it exists) is the largest type that is a subtype of both  $S$  and  $T$ .

Jargon: In the simply typed lambda calculus with subtyping, records, and booleans...

- The subtype relation *has joins*
- The subtype relation *has bounded meets*

# Examples



What are the meets of the following pairs of types?

1.  $\{x: \text{Bool}, y: \text{Bool}\}$  and  $\{y: \text{Bool}, z: \text{Bool}\}$ ?
2.  $\{x: \text{Bool}\}$  and  $\{y: \text{Bool}\}$ ?
3.  $\{x: \{a: \text{Bool}, b: \text{Bool}\}\}$  and  $\{x: \{b: \text{Bool}, c: \text{Bool}\}, y: \text{Bool}\}$ ?
4.  $\{\}$  and  $\text{Bool}$ ?
5.  $\{x: \{\}\}$  and  $\{x: \text{Bool}\}$ ?
6.  $\text{Top} \rightarrow \{x: \text{Bool}\}$  and  $\text{Top} \rightarrow \{y: \text{Bool}\}$ ?
7.  $\{x: \text{Bool}\} \rightarrow \text{Top}$  and  $\{y: \text{Bool}\} \rightarrow \text{Top}$ ?

# Calculating Joins



$$S \vee T = \begin{cases} \text{Bool} & \text{if } S = T = \text{Bool} \\ M_1 \rightarrow J_2 & \text{if } S = S_1 \rightarrow S_2 \quad T = T_1 \rightarrow T_2 \\ & S_1 \wedge T_1 = M_1 \quad S_2 \vee T_2 = J_2 \\ \{j_l : J_l \mid l \in 1..q\} & \text{if } S = \{k_j : S_j \mid j \in 1..m\} \\ & T = \{l_i : T_i \mid i \in 1..n\} \\ & \{j_l \mid l \in 1..q\} = \{k_j \mid j \in 1..m\} \cap \{l_i \mid i \in 1..n\} \\ & S_j \vee T_i = J_l \quad \text{for each } j_l = k_j = l_i \\ \text{Top} & \text{otherwise} \end{cases}$$

# Calculating Meets



$S \wedge T =$

{	$S$	if $T = \text{Top}$
	$T$	if $S = \text{Top}$
	$\text{Bool}$	if $S = T = \text{Bool}$
	$J_1 \rightarrow M_2$	if $S = S_1 \rightarrow S_2$ $T = T_1 \rightarrow T_2$ $S_1 \vee T_1 = J_1$ $S_2 \wedge T_2 = M_2$
	$\{m_l : M_l \mid l \in 1..q\}$	if $S = \{k_j : S_j \mid j \in 1..m\}$ $T = \{l_i : T_i \mid i \in 1..n\}$ $\{m_l \mid l \in 1..q\} = \{k_j \mid j \in 1..m\} \cup \{l_i \mid i \in 1..n\}$ $S_j \wedge T_i = M_l$ for each $m_l = k_j = l_i$ $M_l = S_j$ if $m_l = k_j$ occurs only in $S$ $M_l = T_i$ if $m_l = l_i$ occurs only in $T$
	$\text{fail}$	otherwise

# Homework😊



- Read and digest chapter 16 & 17
- HW#1: 16.2.5
- HW#2: Exercises on Slide p107 & P 111