

Chapter 13: Reference

Why reference Typing Evaluation Store Typings Safety Notes





References



Computational Effects



Also known as *side effects*. A *function* or *expression* is said to have a **side effect** if, in addition to returning a value, it also *modifies some state* or has an *observable interaction with* calling functions or the outside world.

- modify a global variable or static variable, modify one of its arguments,
- raise an exception,
- write data to a display or file, read data, or
- call other side-effecting functions.

In the presence of side effects, a program's behavior may depend on *history*; that is, the *order of evaluation* matters.



Computational Effects



Side effects are the *most common way* that a program *interacts with the outside world* (people, file systems, other computers on networks).

The degree to which side effects are used depends on the *programming paradigm*.

- Imperative programming is known for its frequent utilization of side effects.
- In *functional programming*, side effects are rarely used. Functional languages such as *Standard ML*, *Scheme* and *Scala* do not restrict side effects, but it is customary for programmers to avoid them. The functional language *Haskell* expresses side effects such as I/O and other stateful computations using *monadic* actions.





Mutability

So far, what we have discussed does not yet include *computational effects* (also known as *side effects*). In particular, whenever we defined function, we *never changed variables or data*. Rather, we always computed new data.

- For instance, the operations to insert an item into the data structure *didn't effect the old copy* of the data structure. Instead, we *always built a new data structure* with the item appropriately inserted.
- For the most part, programming in a functional style (i.e., without side effects) is a "good thing" because it's easier to reason locally about the behavior of the program.



Mutability



In most programming languages, *variables are mutable* — i.e., a variable provides both

- a name that refers to a previously calculated value, and
- the possibility of overwriting this value with another (which will be referred to by the same name)
- In some languages (e.g., OCaml), these features are separate:
 - variables are only for naming the binding between a variable and its value is immutable
 - introduce a new class of mutable values (called *reference* cells or *references*)
 - at any given moment, a reference *holds a value* (and can be dereferenced to obtain this value)
 - *a new value* may be assigned to a reference





Mutability

Writing values into memory locations is the fundamental mechanism of imperative languages such as Pascal or C.

Mutable structures are required to implement many *efficient algorithms*. They are also very convenient to represent the *current state of a state machine*.





Basic Examples

```
#let r = ref 5
val r : int ref = {contents = 5}
# r:= !r +2
# !r
-: int = 7
(r:=succ(!r); !r)
(r:=succ(!r); r:=succ(!r); r:=succ(!r); r:=succ(!r); !r)
i.e.,
 (((((r:=succ(!r); r:=succ(!r)); r:=succ(!r)); :=succ(!r));
```





Basic Examples

```
# let flag = ref true;;
```

```
-val flag: bool ref = {contents = true}
```

```
# if !flag then 1 else 2;;
```

```
-: int = 1
```





Reference

Basic operations :

- allocation : ref (operator)
- dereferencing : !
- assignment: :=

Is there any difference between?

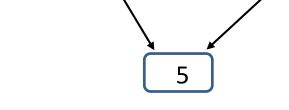




Aliasing

A value of type ref T is a *pointer* to a cell holding a value of type T.

If this value is "copied" by assigning it to another variable, the cell pointed to is not copied. (*r* and *s* are *aliases*)



So we can change **r** by assigning to **s**:

(s:=10; !r)



Aliasing all around us



Reference cells are not the only language feature that introduces the possibility of aliasing.

- arrays
- communication channels
- I/O devices (disks, etc.)



The difficulties of aliasing



The possibility of aliasing *invalidates* all sorts of useful forms of *reasoning about programs*, both *by programmers*...

e.g., function

 λr : *Ref Nat*. λs : *Ref Nat*. $(r \coloneqq 2; s \coloneqq 3; !r)$

always returns 2 unless r and s are aliases.

... and by compilers:

Code motion out of loops, common sub-expression elimination, allocation of variables to registers, and detection of uninitialized variables all depend upon the compiler knowing which objects a load or a store operation could reference.

High-performance compilers spend significant energy on *alias analysis* to try to establish when different variables cannot possibly refer to the same storage.

The benefits of aliasing



The problems of aliasing have led some language designers simply to disallow it (e.g., Haskell).

However, there are good reasons why most languages do provide constructs involving aliasing:

- efficiency (e.g., arrays)
- "action at a distance" (e.g., symbol tables)
- shared resources (e.g., locks) in concurrent systems



Example



$$c = ref 0$$

incc = λx : Unit. ($c \coloneqq succ(!c)$; ! c)
decc = λx : Unit. ($c \coloneqq pred(!c)$; ! c)
incc unit
decc unit
 $o = \{i = incc, d = decc\}$

```
let newcounter = o

\lambda_{.Unit}.

let c = ref \ 0 in

let incc = \lambda x: Unit. (c \coloneqq succ(!c); !c) in

let decc = \lambda x: Unit. (c \coloneqq pred(!c); !c)

let o = \{i = incc, d = decc\} in

o
```

Syntax



t ::=	terms
unit	unit constant
x	variable
λ x:T.t	abstraction
t t	application
ref t	reference creation
!t	dereference
t:=t	assignment

... plus other familiar types, in examples.



Typing rules



 $\frac{\Gamma \vdash t_1 : T_1}{\Gamma \vdash ref \ t_1 : Ref \ T_1}$ (T-REF) $\frac{\Gamma \vdash t_1 : Ref \ T_1}{\Gamma \vdash !t_1 : T_1}$ (T-DEREF) $\frac{\Gamma \vdash t_1 : Ref \ T_1 \qquad (T-DEREF)}{\Gamma \vdash t_1 : Ref \ T_1 \qquad \Gamma \vdash t_2 : T_1}$ (T-ASSIGN)



Example



NatArray = Ref (Nat→Nat);

```
newarray = \lambda_{:}Unit. ref (\lambdan:Nat.0);
: Unit \rightarrow NatArray
```

```
lookup = \lambdaa:NatArray. \lambdan:Nat. (!a) n;
: NatArray \rightarrow Nat \rightarrow Nat
```

```
update = \lambdaa:NatArray. \lambdam:Nat. \lambdav:Nat.
let oldf = !a in
a := (\lambdan:Nat. if equal m n then v else oldf n);
: NatArray \rightarrow Nat \rightarrow Nat \rightarrow Unit
```





What is the value of the expression ref 0?

Crucial observation: evaluating ref 0 must do something ? Is r = ref 0

s = ref 0

and

r = ref 0 s = r

behave the same?

Specifically, evaluating ref 0 should *allocate some storage* and yield a *reference* (or *pointer*) to that storage.

So *what* is a reference?





The store

A reference names a *location* in the *store* (also known as the *heap* or just the *memory*).

What is the **store**?

- *Concretely*: an array of *8-bit bytes*, indexed by 32/64-bit integers.
- *More abstractly*: an array of *values*.
- Even more abstractly: a partial function from locations to values.





Locations

Syntax of *values*:



... and since all values are terms ...



Syntax of Terms



t ::=		terms
	unit	unit constant
	X	variable
	$\lambda \texttt{x:T.t}$	abstraction
	t t	application
	ref t	reference creation
	!t	dereference
	t:=t	assignment
	/	store location



Aside



Does this mean we are going to allow programmers to *write explicit locations* in their programs??

No: This is just a modeling trick.

We are enriching the "source language" to include some *runtime structures*, so that we can continue to *formalize evaluation* as a relation between source terms.

Aside: If we formalize evaluation in the *big-step style*, then we can *add locations* to *the set of values* (results of evaluation) without adding them to the set of terms.





The *result* of *evaluating a term* now (with references)

- depends on the store in which it is evaluated.
- is not just a value we must also keep track of the changes that get made to the store.
- i.e., the evaluation relation should now map *a term as* well as *a store* to *a reduced term and a new store*.

$$t \mid \mu \rightarrow t' \mid \mu'$$

To use the metavariable μ to *range over stores*.





An assignment $t_1 \coloneqq t_2$ first evaluates t_1 and t_2 until they become values ...

$$\frac{\mathbf{t}_{1} \mid \mu \longrightarrow \mathbf{t}_{1}' \mid \mu'}{\mathbf{t}_{1} := \mathbf{t}_{2} \mid \mu \longrightarrow \mathbf{t}_{1}' := \mathbf{t}_{2} \mid \mu'} \quad (\text{E-ASSIGN1})$$

$$\frac{\mathbf{t}_{2} \mid \mu \longrightarrow \mathbf{t}_{2}' \mid \mu'}{\mathbf{v}_{1} := \mathbf{t}_{2} \mid \mu \longrightarrow \mathbf{v}_{1} := \mathbf{t}_{2}' \mid \mu'} \quad (\text{E-ASSIGN2})$$

... and then returns unit and updates the store:

 $I := v_2 \mid \mu \longrightarrow \text{unit} \mid [I \mapsto v_2] \mu$ (E-ASSIGN)





A term of the form ref t_1 first evaluates inside t_1 until it becomes a value ...

$$\frac{\mathtt{t}_1 \mid \mu \longrightarrow \mathtt{t}'_1 \mid \mu'}{\texttt{ref } \mathtt{t}_1 \mid \mu \longrightarrow \texttt{ref } \mathtt{t}'_1 \mid \mu'} \qquad (\text{E-ReF})$$

... and then *chooses* (allocates) a *fresh location l*, *augments* the store with a binding from *l* to v_1 , and returns *l*:

$$\frac{l \notin \textit{dom}(\mu)}{\texttt{ref } \texttt{v}_1 \mid \mu \longrightarrow l \mid (\mu, \, l \mapsto \texttt{v}_1)}$$



(E-RefV)



A term $!t_1$ first evaluates in t_1 until it becomes a value...

 $\frac{\mathtt{t}_1 \mid \mu \longrightarrow \mathtt{t}'_1 \mid \mu'}{\mathtt{!t}_1 \mid \mu \longrightarrow \mathtt{!t}'_1 \mid \mu'} \qquad (\text{E-DEREF})$

... and then *looks up this value* (which must be a location, if the original term was well typed) and returns its contents in the current store

$$\frac{\mu(l) = \mathbf{v}}{! \, l \mid \mu \longrightarrow \mathbf{v} \mid \mu}$$

(E-DEREFLOC)





Evaluation rules for *function abstraction* and *application* are **augmented with stores**, but *don't do anything* with them directly.

$$\begin{array}{l} \begin{array}{c} \mathbf{t}_{1} \mid \mu \longrightarrow \mathbf{t}_{1}' \mid \mu' \\ \hline \mathbf{t}_{1} \mid \mathbf{t}_{2} \mid \mu \longrightarrow \mathbf{t}_{1}' \mid \mathbf{t}_{2} \mid \mu' \end{array} & (\text{E-APP1}) \\ \\ \end{array} \\ \begin{array}{c} \mathbf{t}_{2} \mid \mu \longrightarrow \mathbf{t}_{2}' \mid \mu' \\ \hline \mathbf{v}_{1} \mid \mathbf{t}_{2} \mid \mu \longrightarrow \mathbf{v}_{1} \mid \mathbf{t}_{2}' \mid \mu' \end{array} & (\text{E-APP1}) \end{array}$$

 $(\lambda \mathbf{x}: \mathbf{T}_{11}.\mathbf{t}_{12}) \ \mathbf{v}_2 \mid \mu \longrightarrow [\mathbf{x} \mapsto \mathbf{v}_2] \mathbf{t}_{12} \mid \mu (\text{E-APPABS})$





Aside

Garbage Collection

Note that we are not modeling *garbage collection* — the store just *grows without bound*.

It may not be problematic for most *theoretical purposes*, whereas it is clear that for *practical purposes* some form of *deallocation* of unused storage must be provided.

Pointer Arithmetic

p++; We can't do any!





Store Typing



Typing Locations



Question: What is the *type of a location*?

Answer: Depends on the contents of the store!

For example, in the store $(l_1 \mapsto \text{unit}, l_2 \mapsto \text{unit})$, the term $!l_2$ is evaluated to unit, having type Unit.

But in the store $(l_1 \mapsto \text{unit}, l_2 \mapsto \lambda x: \text{Unit. } x)$, the term $|l_2|$ has type Unit \rightarrow Unit.



Typing Locations — first try

Roughly, to find the type of a location l, first *look up* the current contents of l in the store, and calculate the type T_1 of the contents: $\frac{\Gamma \vdash \mu(l) : T_1}{\Gamma \vdash l : \text{Ref } T_1}$

More precisely, to make the type of a term depend on the store (keeping a consistent state), we should change the *typing relation* from *three-place* to :

 $\frac{\Gamma \mid \mu \vdash \mu(I) : \mathtt{T}_1}{\Gamma \mid \mu \vdash I : \mathtt{Ref } \mathtt{T}_1}$

i.e., typing is now a *four-place relation* (about *contexts*, *stores*, *terms*, and *types*), though the store is a part of the context

Problems #1

However, this rule is not *completely satisfactory*, and is *rather inefficient*.

- First of all, it can make typing derivations very large (if a location appears many times in a term) !
- e.g., if

$$u = l_1 \mapsto \lambda x: \text{Nat. 999},$$

$$l_2 \mapsto \lambda x: \text{Nat. } (! l_1) x,$$

$$l_3 \mapsto \lambda x: \text{Nat. } (! l_2) x,$$

$$l_4 \mapsto \lambda x: \text{Nat. } (! l_3) x,$$

$$l_5 \mapsto \lambda x: \text{Nat. } (! l_4) x),$$

then how big is the typing derivation for l_5 ?



Problems #2

But wait... it *gets worse* if the store contains a *cycle*. Suppose

$$\mu = l_1 \mapsto \lambda x: \text{Nat. } (! l_2) x,$$
$$l_2 \mapsto \lambda x: \text{Nat. } (! l_1) x),$$

how big is the typing derivation for l_2 ? Calculating a type for l_2 requires finding the type of l_1 , which in turn involves l_2 .





Why?

What leads to the problems?

Our typing rule for locations requires us to *recalculate the type of a location every time it's* mentioned in a term, which should not be necessary.

In fact, once a location is first created, *the type of the initial value* is known, and *the type will be kept* even if the values can be changed.





Store Typing

Observation:

The typing rules we have chosen for references guarantee *that a given location* in the store is *always* used to hold *values of the same type*.

These intended types can be collected into a *store typing:*

— a *partial function* from *locations* to *types*.



Store Typing



E.g., for

$$\mu = l_1 \mapsto \lambda x: \text{Nat. 999},$$

$$l_2 \mapsto \lambda x: \text{Nat. } (! l_1) \times,$$

$$l_3 \mapsto \lambda x: \text{Nat. } (! l_2) \times,$$

$$l_4 \mapsto \lambda x: \text{Nat. } (! l_3) \times,$$

$$l_5 \mapsto \lambda x: \text{Nat. } (! l_4) \times),$$

A reasonable *store typing* would be

$$\Sigma = (I_1 \mapsto \texttt{Nat} o \texttt{Nat}, \ I_2 \mapsto \texttt{Nat} o \texttt{Nat}, \ I_3 \mapsto \texttt{Nat} o \texttt{Nat}, \ I_4 \mapsto \texttt{Nat} o \texttt{Nat}, \ I_5 \mapsto \texttt{Nat} o \texttt{Nat})$$





Now, suppose we are given *a store typing* Σ describing the store μ in which we intend to evaluate some term t. Then we can use Σ to look up the types of locations in t instead of calculating them from the values in μ .

 $\frac{\Sigma(I) = T_1}{\Gamma \mid \Sigma \vdash I : \text{Ref } T_1}$ (T-Loc)

i.e., *typing* is now a *four-place relation on* contexts, *store typings*, terms, and types.

Proviso: the typing rules accurately predict the results of evaluation *only if* the concrete store used during evaluation actually *conforms to* the store typing.

Final typing rules



 $\Sigma(I) = T_1$ (T-Loc) $\Gamma \mid \Sigma \vdash I : \text{Ref } T_1$ $\Gamma \mid \Sigma \vdash t_1 : T_1$ (T-Ref) $\left[\Sigma \vdash t_1 : \text{Ref } T_{11} \right]$ (T-DEREF) $\Gamma \mid \Sigma \vdash !t_1 : T_{11}$ $\Gamma \mid \Sigma \vdash t_1 : \text{Ref } T_{11} \qquad \Gamma \mid \Sigma \vdash t_2 : T_{11}$ (T-Assign) $\Gamma \mid \Sigma \vdash t_1 := t_2 : Unit$



Question: Where do *these store typings* come from?

Answer: When we first typecheck a program, there will be no explicit locations, so we can use *an empty store typing*, since the locations arise only in terms that are *the intermediate results* of evaluation.

So, when a new location is created during evaluation,

 $\frac{l \notin dom(\mu)}{\operatorname{ref} v_1 \mid \mu \longrightarrow l \mid (\mu, l \mapsto v_1)}$ (E-REFV)

we can observe the type of v_1 and extend the "current store typing" appropriately.





Store Typing

As evaluation proceeds and new locations are created, the store typing is extended by looking at the type of the initial values being placed in newly allocated cells.

 \sum only records the *association* between *already-allocated storage cells* and *their types*.





Safety









How to express the statement of preservation?

First attempt: just add *stores* and *store typings* in the appropriate places.

Theorem(?): if $\Gamma \mid \Sigma \vdash t: T$ and $t \mid \mu \longrightarrow t' \mid \mu'$, then $\Gamma \mid \Sigma \vdash t': T$

Right?? Wrong!

Why wrong?

Because Σ and μ here are not constrained to have anything to do with each other!





Definition: A store μ is said to be *well typed* with respect to a typing context Γ and a store typing Σ , written $\Gamma \mid \Sigma \vdash \mu$, if $dom(\mu) = dom(\Sigma)$ and $\Gamma \mid \Sigma \vdash \mu(l)$: $\Sigma(l)$ for every $l \in dom(\mu)$.

Theorem (?): if $\Gamma \mid \Sigma \vdash t: T$ $t \mid \mu \longrightarrow t' \mid \mu'$ $\Gamma \mid \Sigma \vdash \mu$ then $\Gamma \mid \Sigma \vdash t': T$

Right this time? Still wrong ! Why?





Creation of a *new reference cell* ...

 $\frac{l \notin dom(\mu)}{\operatorname{ref} v_1 \mid \mu \longrightarrow l \mid (\mu, l \mapsto v_1)}$

(E-REFV)

... breaks the correspondence between the store typing and the store.

Since *the store can grow during evaluation*:

Creation of a new reference cell yields a store with a *larger domain* than the initial one, making the conclusion incorrect: if μ' includes a binding for a fresh location l, then l cann't be in the domain of Σ , and it will not be case that t' is typable under Σ .





A correct version.

What is Σ' ?

Proof: Easy extension of the preservation proof for λ





Progress





Progress

Theorem:

Suppose t is a closed, well-typed term (*that is*,

 $\Gamma \mid \Sigma \vdash t: T$ for some T and Σ).

Then either t is a *value* or else, for any store μ such that $\Gamma \mid \Sigma \vdash \mu$, there is some term t' and store μ' with t $\mid \mu \rightarrow$ t' $\mid \mu'$.





In summary ...







We added to λ_{\rightarrow} (with Unit) syntactic forms for *creating*, *dereferencing*, and *assigning* reference cells, plus a new type constructor Ref.

t	::=	terms	
		unit	unit constant
		x	variable
		$\lambda \texttt{x:T.t}$	abstraction
		t t	application
		ref t	reference creation
		!t	dereference
		t:=t	assignment
		1	store location





Evaluation becomes a *four-place* relation: $t \mid \mu \rightarrow t' \mid \mu'$

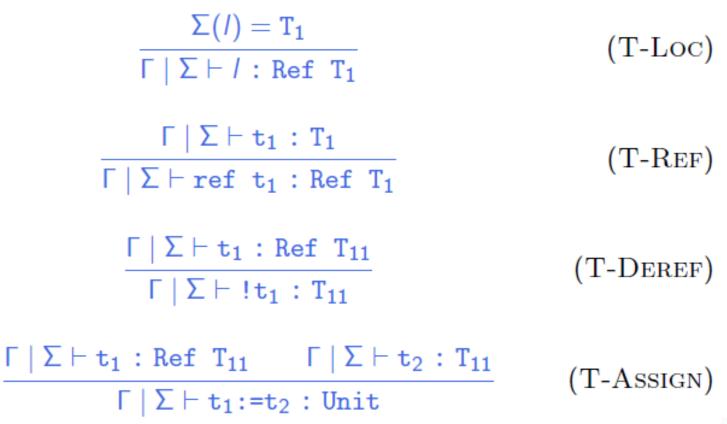
 $\frac{l \notin dom(\mu)}{\operatorname{ref} v_1 \mid \mu \longrightarrow l \mid (\mu, l \mapsto v_1)} \quad (\text{E-REFV})$ $\frac{\mu(l) = v}{|l \mid \mu \longrightarrow v \mid \mu} \quad (\text{E-DEREFLOC})$ $l := v_2 \mid \mu \longrightarrow \operatorname{unit} \mid [l \mapsto v_2]\mu \quad (\text{E-ASSIGN})$







Typing becomes a *three-place* relation: $\Gamma \mid \Sigma \vdash t : T$







Theorem: if $\Gamma \mid \Sigma \vdash t: T
 \Gamma \mid \Sigma \vdash \mu
 t \mid \mu \longrightarrow t' \mid \mu'
 then, for some <math>\Sigma' \supseteq \Sigma$, $\Gamma \mid \Sigma' \vdash t': T
 \Gamma \mid \Sigma' \vdash \mu'.$



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Progress

Theorem: Suppose t is a closed, well-typed term (that is, $\emptyset \mid \Sigma \vdash t: T$ for some T and Σ). Then either t is a value or else, for any store μ such that $\emptyset \mid \Sigma \vdash \mu$, there is some term t' and store μ' with t $\mid \mu \rightarrow t' \mid \mu'$.





Others ...





Arrays

Fix-sized vectors of values. All of the values must have the *same type*, and the fields in the array can be accessed and modified.

e.g., in Ocaml, arrays can be created with $[|e_1; ...; e_n|]$

```
# let a = [|1;3;5;7;9|];;
val a : int array = [|1;3;5;7;9|]
#a;;
-: int array = [|1;3;5;7;9|]
```



Recursion via references



Indeed, we can define *arbitrary recursive functions* using references.

1. Allocate a ref cell and initialize it with a *dummy function* of the appropriate type:

fact_{*ref*} = ref (λ n: Nat. 0)

2. Define the body of the function we are interested in, using the contents of the reference cell for making recursive calls:

 $fact_{body} =$

λn: Nat.

if is zero n then 1 else times n ((! $fact_{ref}$)(pred n))

- 3. "Backpatch" by storing the real body into the reference cell: fact_{ref}: = fact_{body}
- 4. Extract the contents of the reference cell and use it as desired: fact = ! fact_{ref} fact 5



Homework[©]

- Read chapter 13
- Read and chew over the codes of *fullref*.
- HW: 13.1.2 and 13.5.8
- Preview chapter 14



Non-termination via references

There are *well-typed terms* in this system that are not strongly normalizing. For example:

t1 = λ r: Ref (Unit → Unit). (r := (λ x: Unit. (!r)x); (!r) unit); t2 = ref (λ x: Unit. x);

Applying t1 to t2 yields a (well-typed) divergent term.





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t1 =
$$\lambda$$
r: Ref (Unit → Unit).
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Applying t1 to t2 yields a (well-typed) divergent term.

