











3















• Idea from Hindley (1969) and Milner (1978) for calculating "best" solution to constraint sets.

Definition: A substitution σ is less specific (or more general) than a substitution σ' , written $\sigma \sqsubseteq \sigma'$, if

 $\sigma' = \gamma \circ \sigma$

for some substitution γ .

Definition: A principal unifier (or sometimes most general unifier) for a constraint set C is a substitution σ that satisfies C and such that $\sigma \sqsubseteq \sigma'$ for every substitution σ' satisfying C.





















- 1. Find a principle type T1 of t1.
- 2. Generalize T1 to a schema ∀X1...Xn.T1.
- 3. Extend the context with $(x, \forall X1...Xn.T1)$.
- Each time we encounter an occurrence of x in t2, look up its type scheme ∀X1...Xn.T1, generate fresh type variables Y1...Yn to instantiate the type scheme, yielding [X1 -> Y1,..., Xn -> Yn]T1, which we use as the type of x



